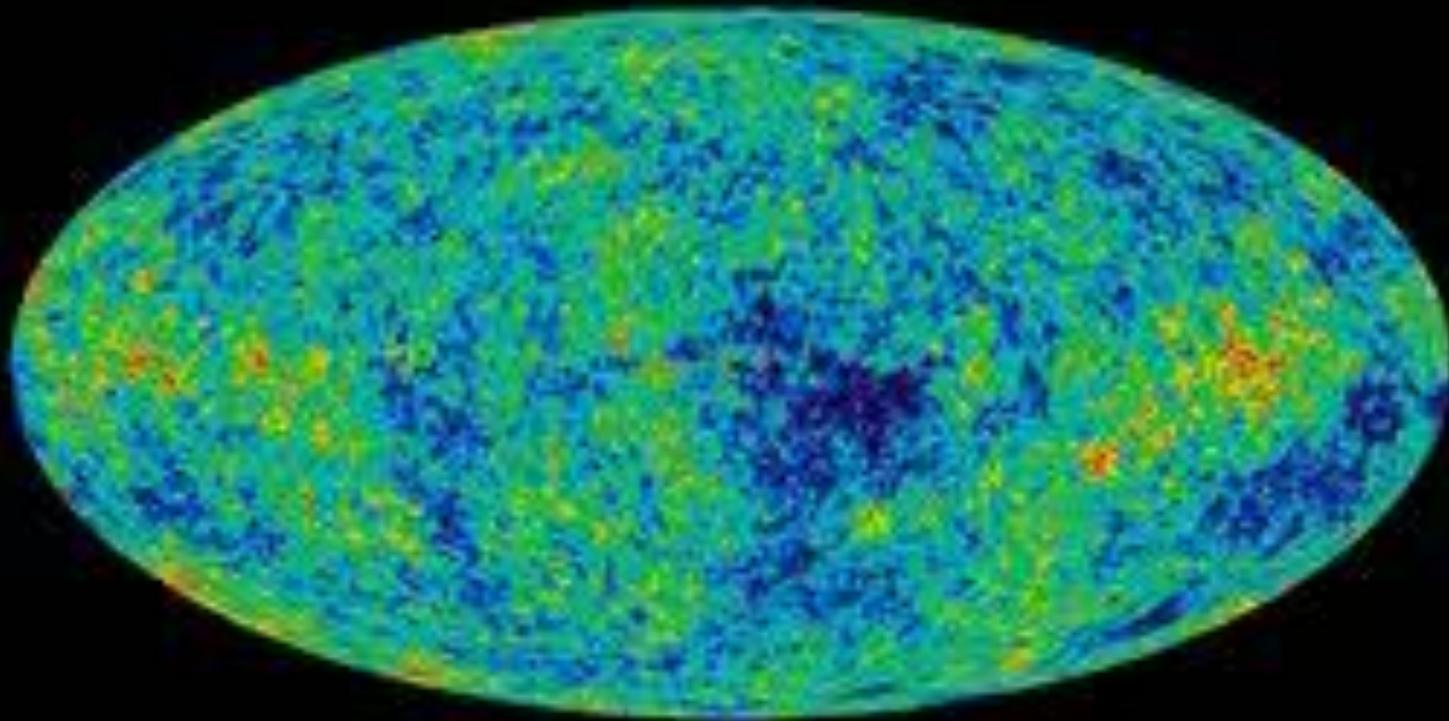


Clusters, voids and their profiles

Ravi K Sheth (Penn/ICTP)

- Halo abundances and clustering
 - Solving Press-Schechter (with Musso)
 - Excursion set peaks (with Paranjape); combines peak theory with Press-Schechter
 - Scale and k -dependent bias is generic
 - Tidal shear makes clustering anisotropic (with Chan, Scoccimarro, Papai)
- Voids
 - Excursion set troughs
 - Under-dense regions can have no large scale bias
 - Profiles (with Castorina, Massara, Varghese)

WMAP of Distant Universe



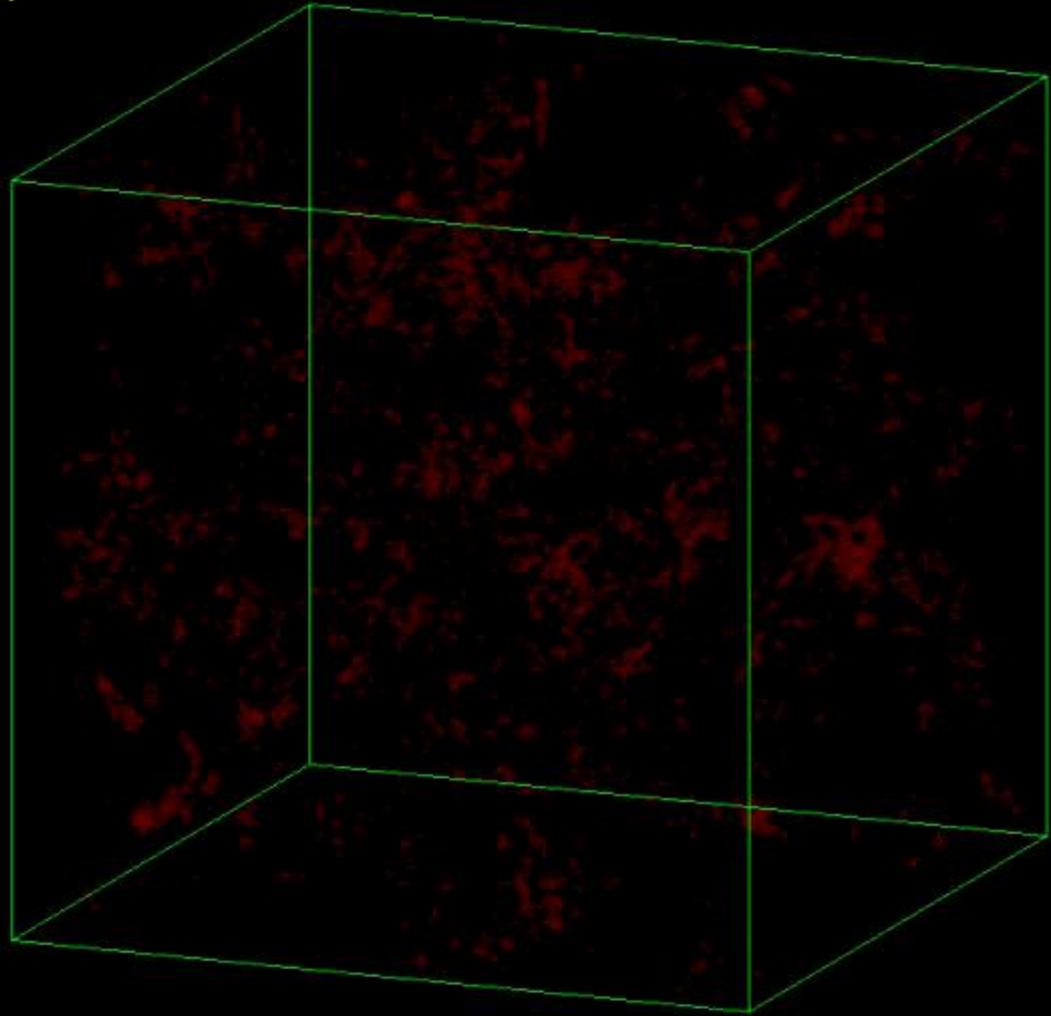
Cold Dark Matter

- **Cold:** speeds are non-relativistic
 - To illustrate, $1000 \text{ km/s} \times 10 \text{ Gyr} \approx 10 \text{ Mpc}$; from $z \sim 1000$ to present, nothing (except photons!) travels more than $\sim 10 \text{ Mpc}$
- **Dark:** no idea (yet) when/where the stars light-up
- **Matter:** gravity the dominant interaction

Cold Dark Matter

- Simulations include gravity only (no gas)
- Late-time field retains memory of initial conditions
- Cosmic capitalism

15.67



Co-moving volume ~ 100 Mpc/h

$R = 6.0 \text{ Mpc}$

$z = 10.155$

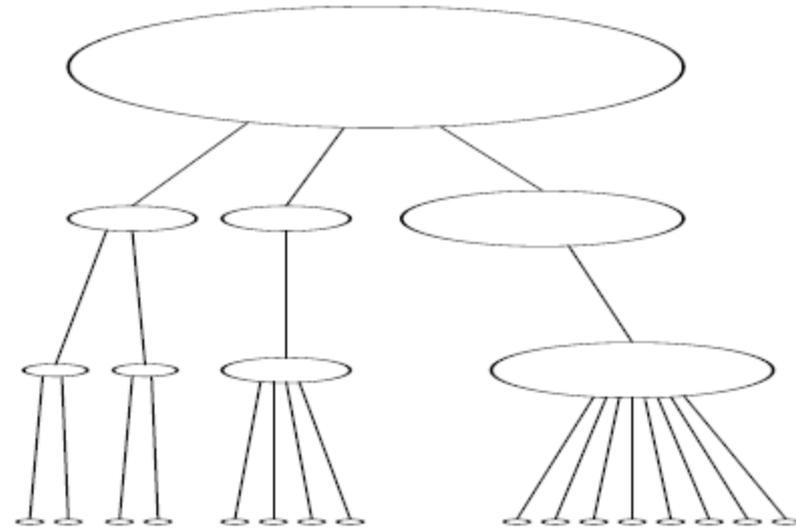
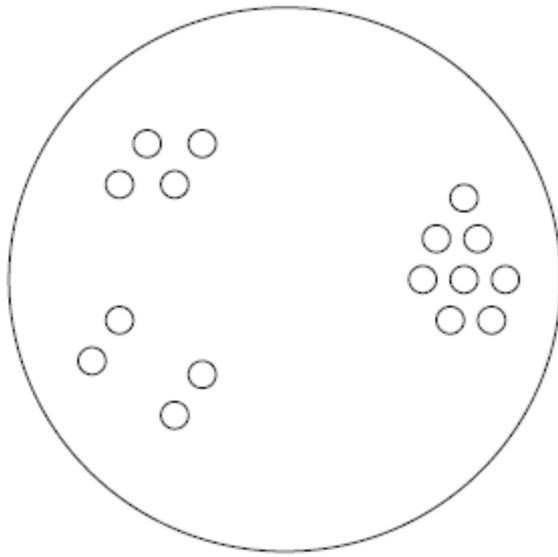
Halo formation



$a = 0.090$

diemand 2003

Initial conditions determine merger history
stochastic



(Mo & White 1996; Sheth 1996)

Birkhoff's theorem important

Halo-
model

≈

Circles in
circles

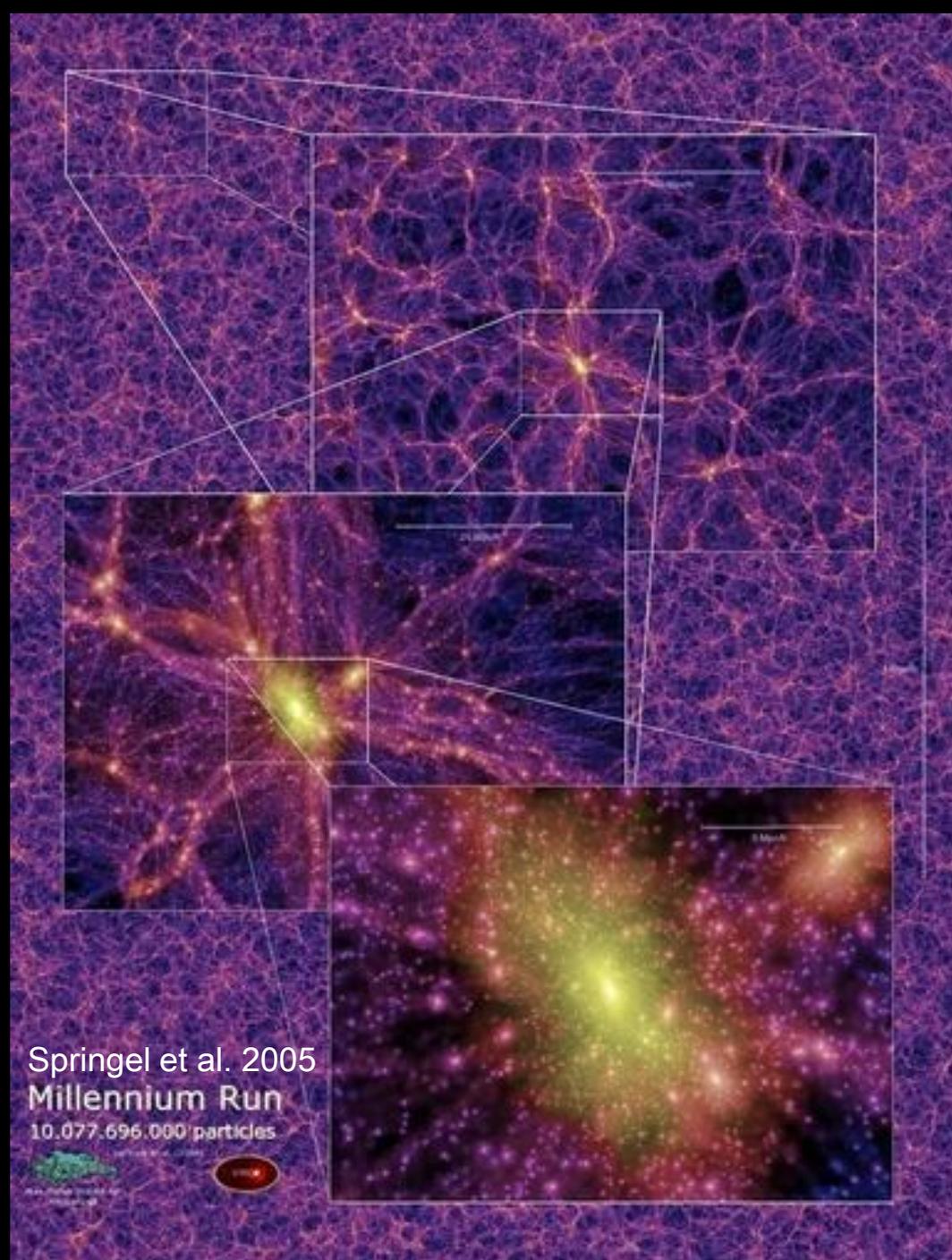


Hierarchical models

Dark matter 'haloes' are basic building blocks of 'nonlinear' structure

Galaxies form in the halos

Galaxy formation depends on halo formation



Models of halo abundances
and clustering:
Gravity in an expanding universe

Goal:

Use knowledge of initial conditions
(CMB) to make inferences about
late-time, nonlinear structures

THE EXCURSION SET APPROACH

Halo abundances: Epstein (1983); Bond et al. (1991)

Halo mergers/formation: Lacey & Cole (1993)

Clustering/environment: Mo & White (1996)

Counts-in-cells: Sheth (1998); Lam & Sheth (2008)

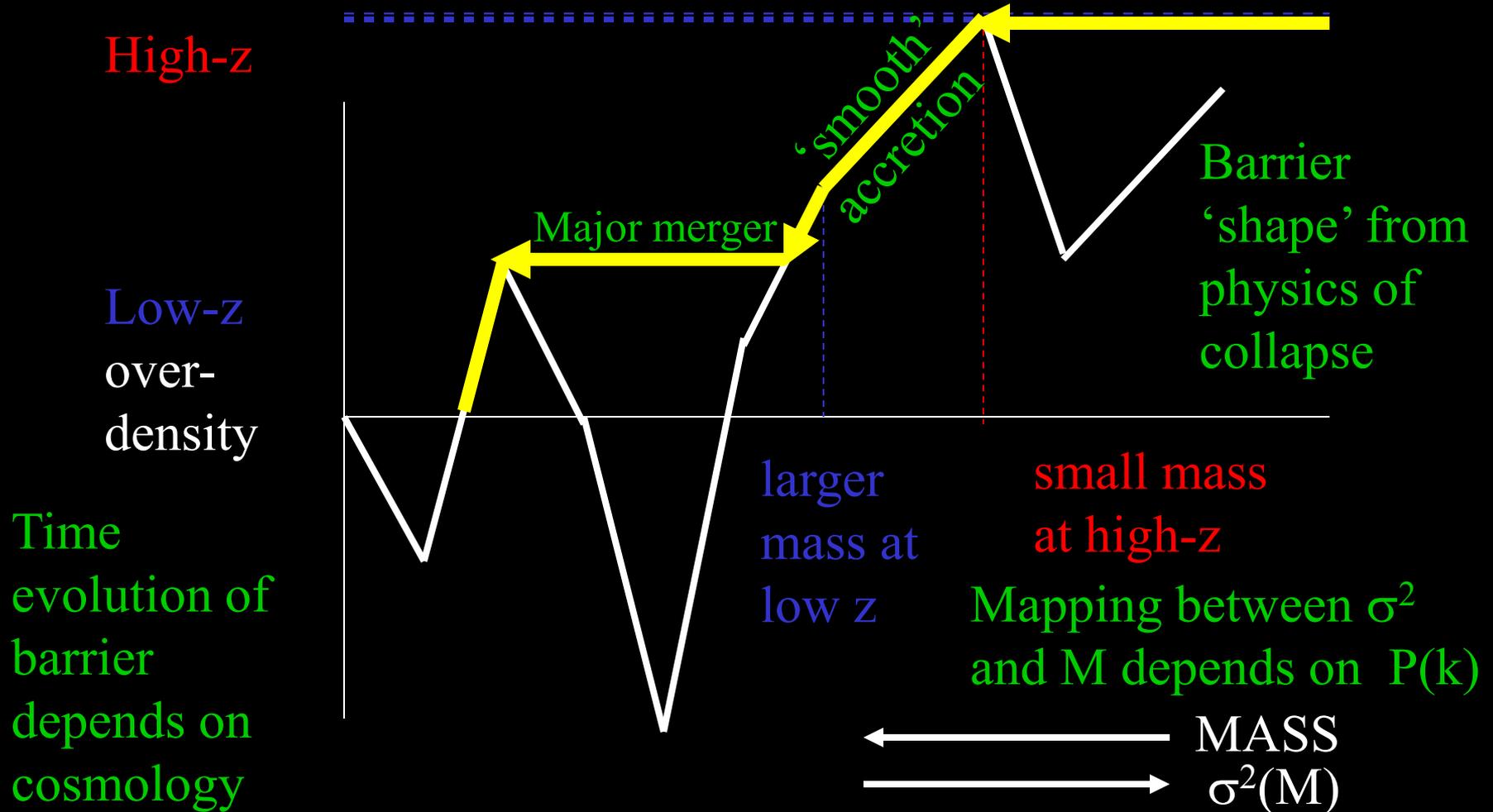
Voids: Sheth & van de Weygaert (2004); Paranjape et al. (2011)

Filaments and sheets: Shen et al. (2006)

Correlated steps and peaks theory: Musso & Sheth (2012)



The excursion set approach



From Walks to Halos: Ansätze

- $f(\delta_c, s) ds$ = fraction of walks which first cross $\delta_c(z)$ at s
 - \approx fraction of initial volume in patches of comoving volume $V(s)$ which were just dense enough to collapse at z
 - \approx fraction of initial mass in regions which each initially contained $m = \rho V(1 + \delta_c) \approx \rho V(s)$ and which were just dense enough to collapse at z (ρ is comoving density of background)
 - $\approx dm \int m n(m, \delta_c) / \rho$

Simplification because...

- Everything local
- Evolution determined by cosmology (competition between gravity and expansion)
- Statistics determined by initial fluctuation field: since Gaussian, statistics specified by initial power-spectrum $P(k)$
- Fact that only very fat cows are spherical is a detail (*crucial* for precision cosmology); in excursion set approach, mass-dependent barrier height increases with distance along walk

Path integrals ...

Press-Schechter: Want $\delta \geq \delta_c$

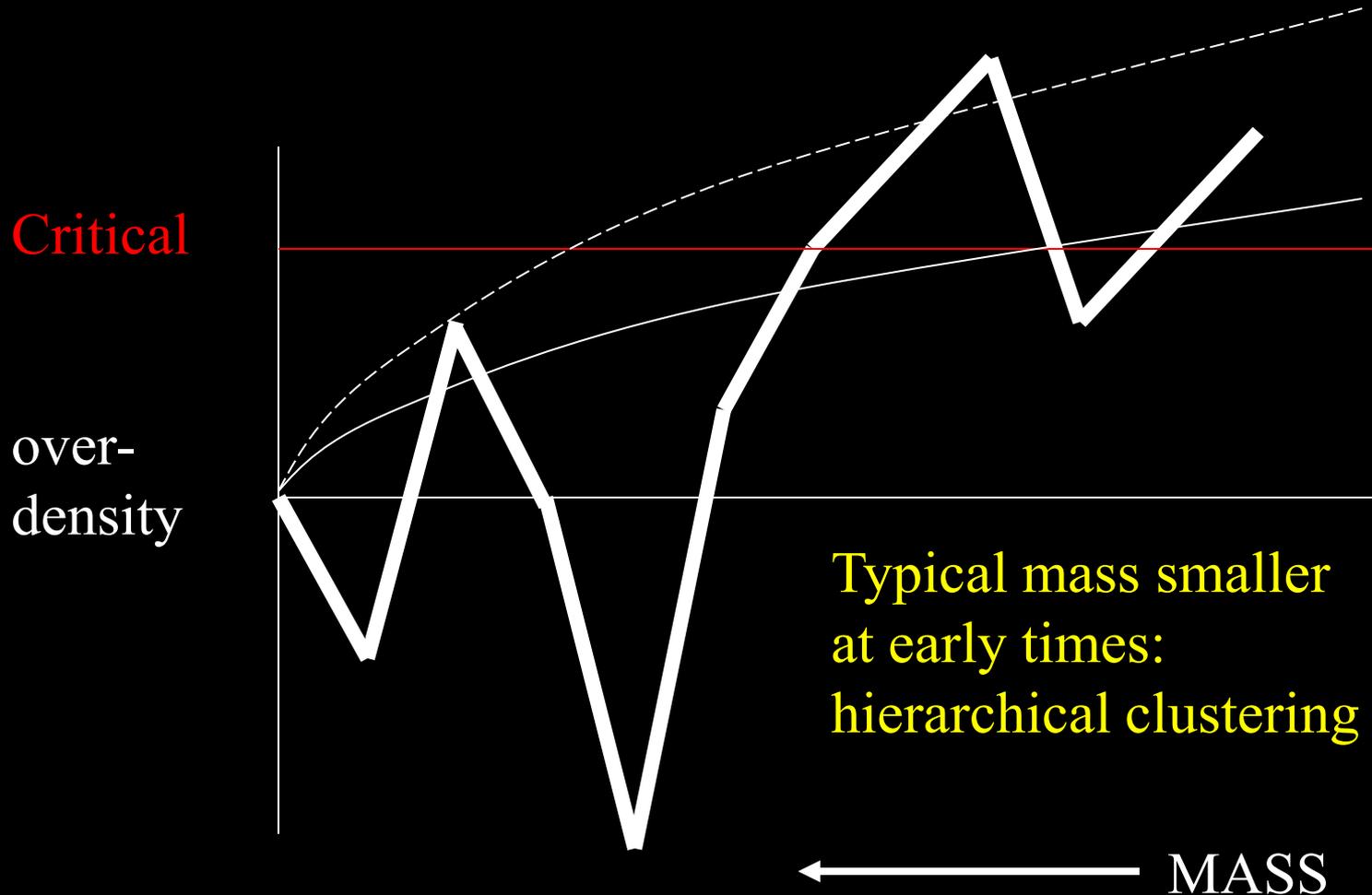
Bond, Cole, Efsthathiou, Kaiser:
 $\delta(s) \geq \delta_c$ and $\delta(S) \leq \delta_c$ for all $S \leq s$:

$$f(s)\Delta s = \int_{-\infty}^{\delta_c} d\delta_1 \cdots \int_{-\infty}^{\delta_c} d\delta_{n-1} \int_{\delta_c}^{\infty} d\delta_n p(\delta_1, \dots, \delta_n)$$

Since $s = n\Delta s$ this requires n -point
distribution in limit as $n \rightarrow \infty$ and $\Delta s \rightarrow 0$.
(Best solved by Monte-Carlo methods.)

... yield little/no insight

Key insight: Think of walks with
'completely correlated' steps



First Crossing Distribution

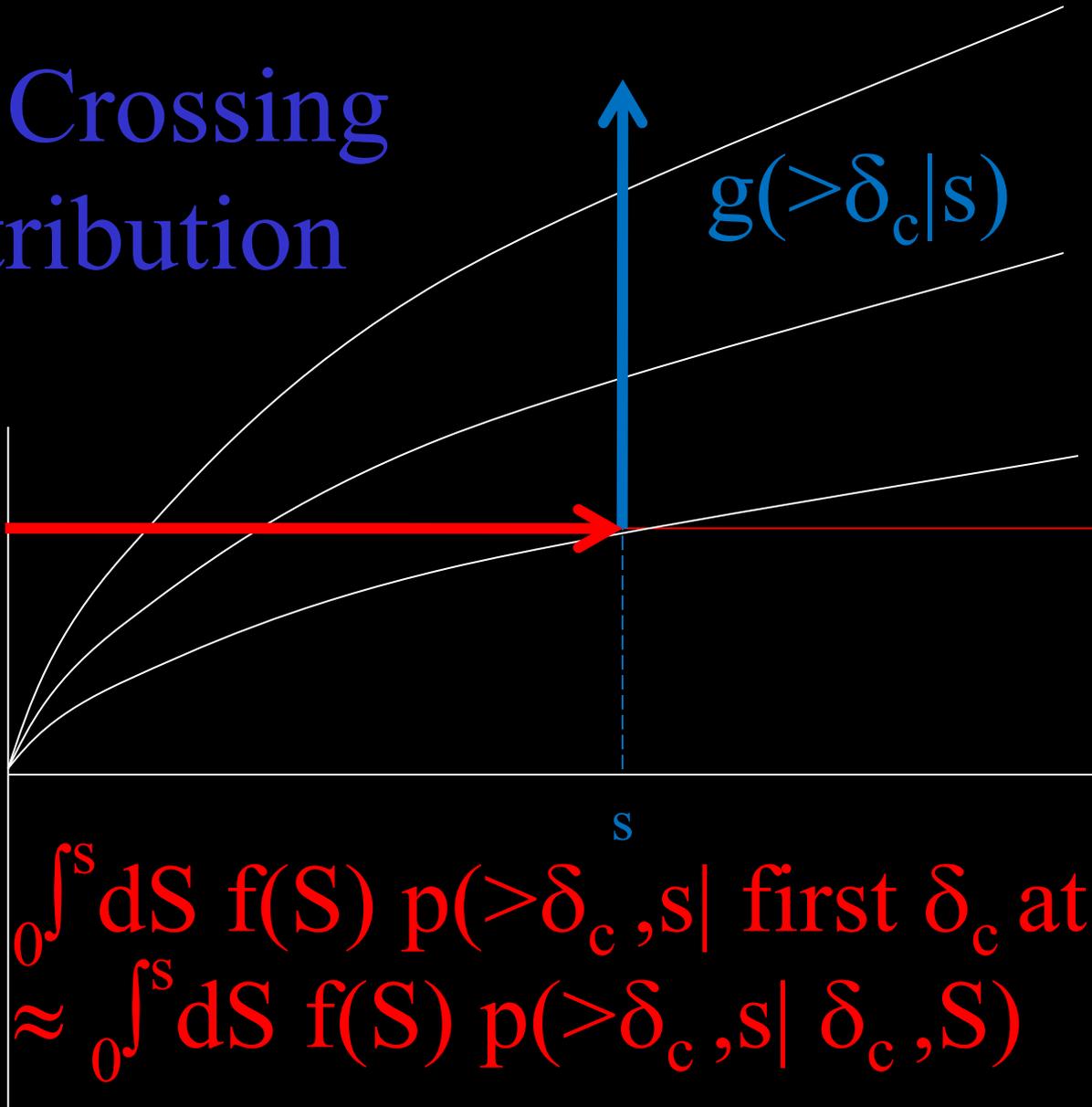
$g(>\delta_c|s)$

Critical

over-
density

s

$$\int_0^s dS f(S) p(>\delta_c, s | \text{first } \delta_c \text{ at } S) \approx \int_0^s dS f(S) p(>\delta_c, s | \delta_c, S)$$



First crossing distributions

- Smooth walks: $p(>\delta_c, s | \delta_c, S, \text{first}) = 1$
- Uncorrelated steps: $p(>\delta_c, s | \delta_c, S, \text{first}) = 1/2$
 - This is the Press-Schechter factor of 2
 - $s f(s) = dg(>\delta|s)/d\ln s = \delta_c \exp(-\delta_c^2/2s) / \sqrt{2\pi s}$
 - Self-similar in units of $v = \delta_c/\sqrt{s}$
- Correlated steps somewhere in between
 - NB. Easy if $p(>\delta_c, s | \delta_c, S, \text{first}) =$ separable function of s and S

For correlated steps
rather than thinking of a walk
as a list of heights
(i.e. the path integrals of Bond et al 1991),
it is more efficient to think of it
as a curve specified by
its height on one scale and
its derivatives

Correlated steps

Require walk below barrier on scale just larger than s , but above barrier on scale s :

$$f(s)ds \approx \int d\delta' \int d\delta \ p(\delta, \delta') \quad \text{where}$$

$$\delta_c < \delta < \delta_c + \Delta s \quad \delta' > 0$$

$$= \Delta s \ p(\delta_c, s) \int d\delta' \ p(\delta' | \delta_c) \ \delta'$$

Reduces problem from $n \gg 1$ dimensions, to just 2

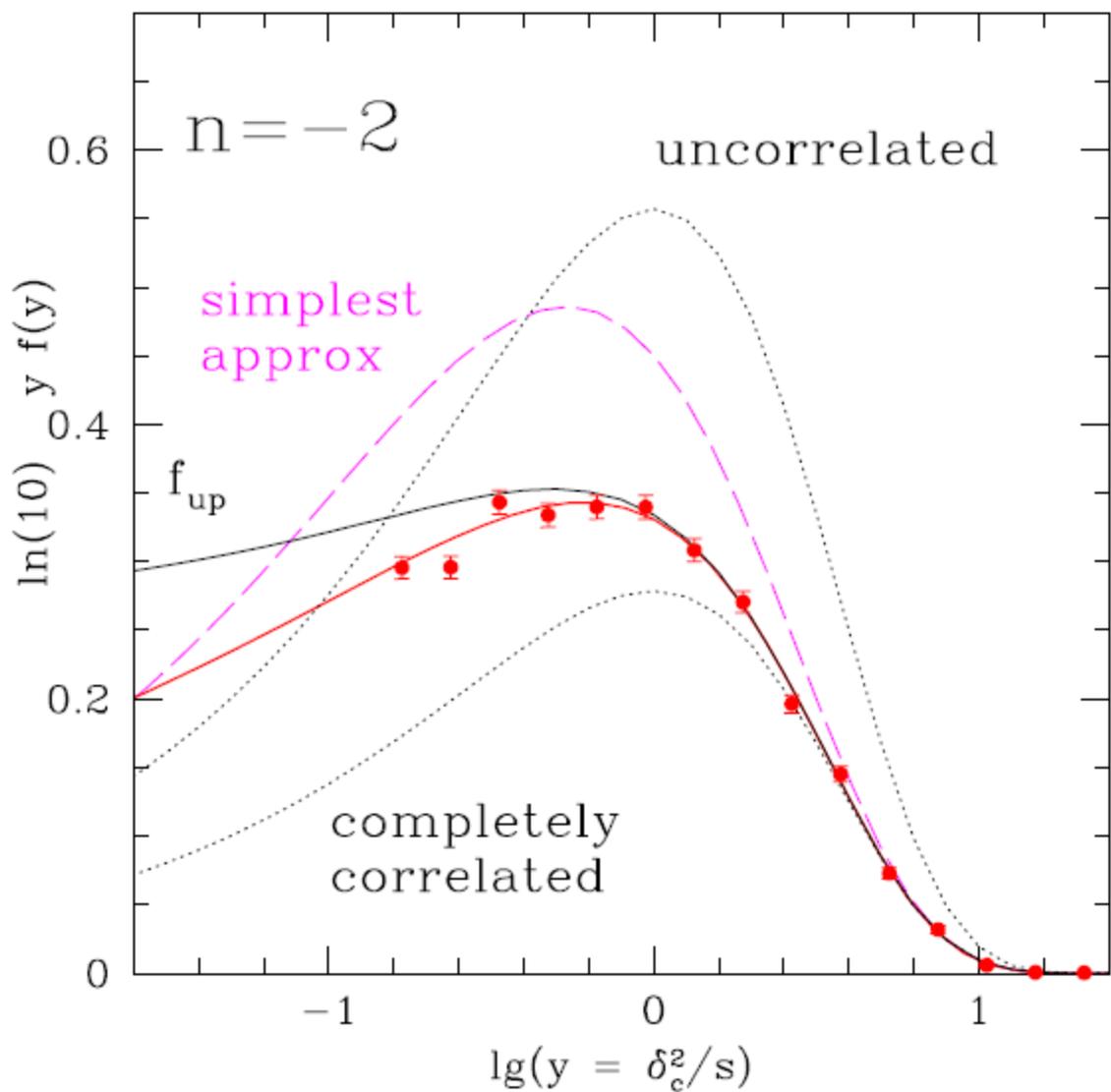
Generalizes trivially to any barrier shape and also for non-Gaussian fields (Musso & Sheth 2012, 2014)

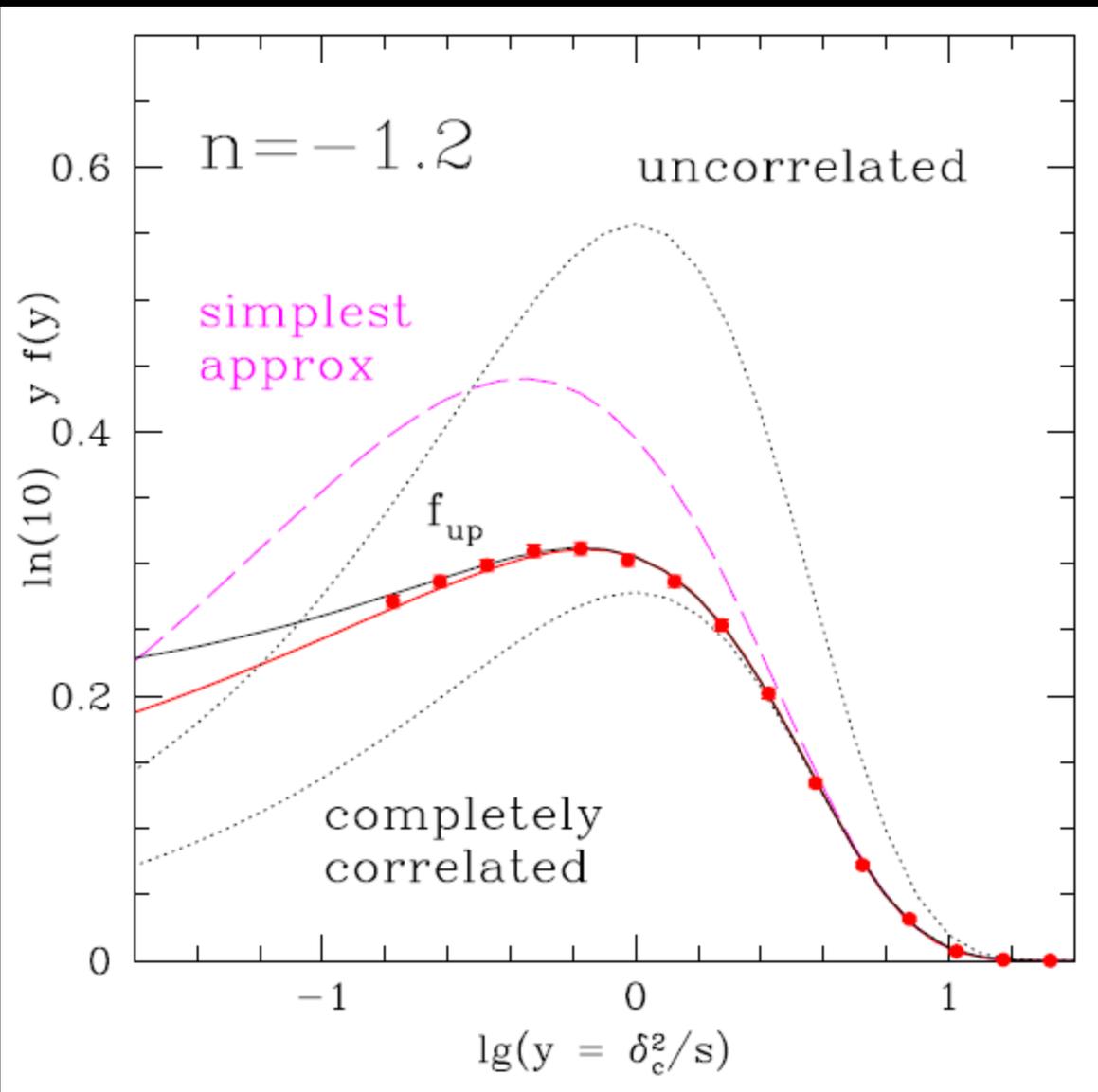
Correlated steps (constant barrier)

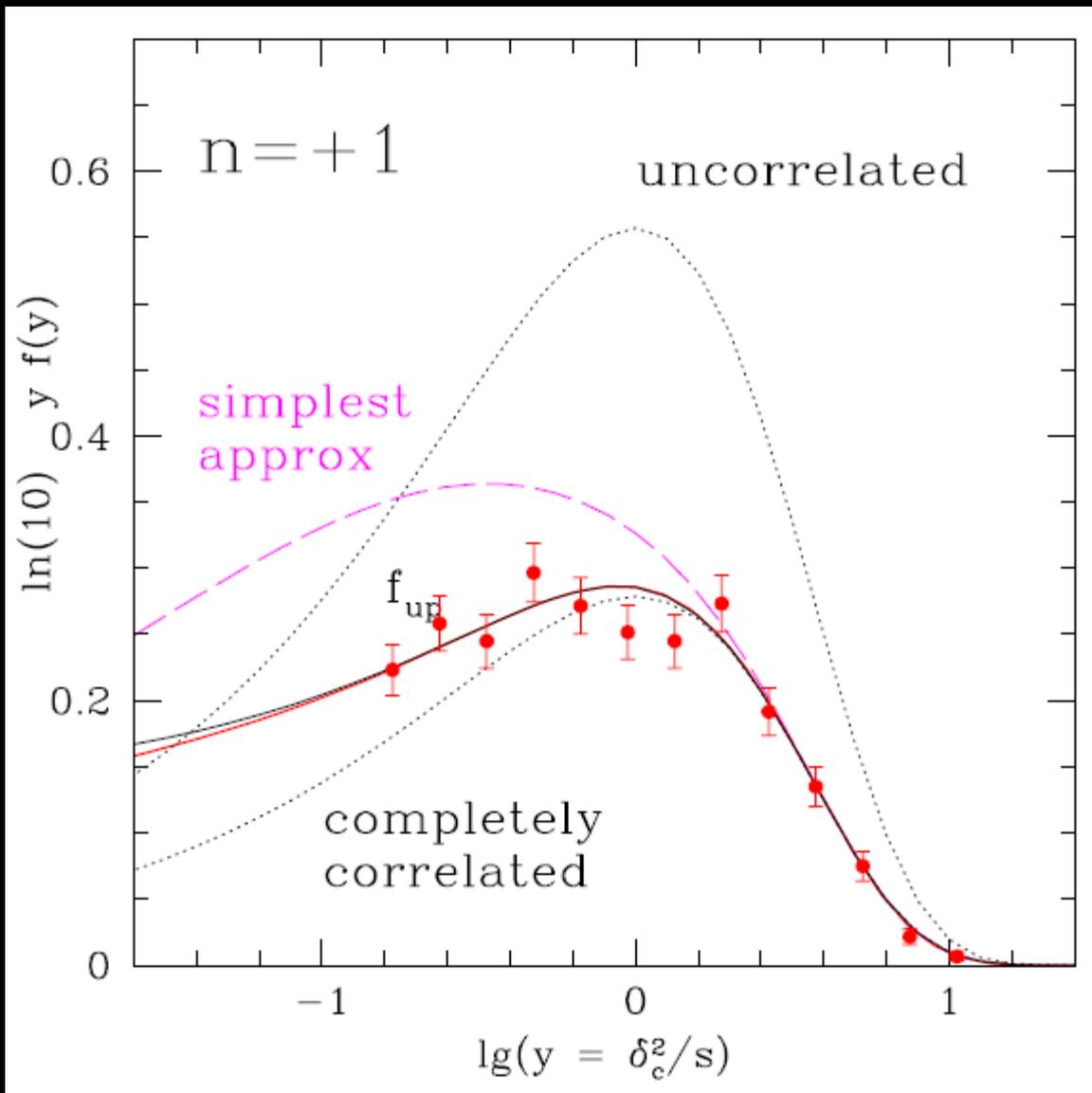
$$\nu f(\nu) = \frac{\nu e^{-\nu^2/2}}{\sqrt{2\pi}} \left[\frac{1 + \operatorname{erf}(\Gamma\nu/\sqrt{2})}{2} + \frac{e^{-\Gamma^2\nu^2/2}}{\sqrt{2\pi}\Gamma\nu} \right]$$

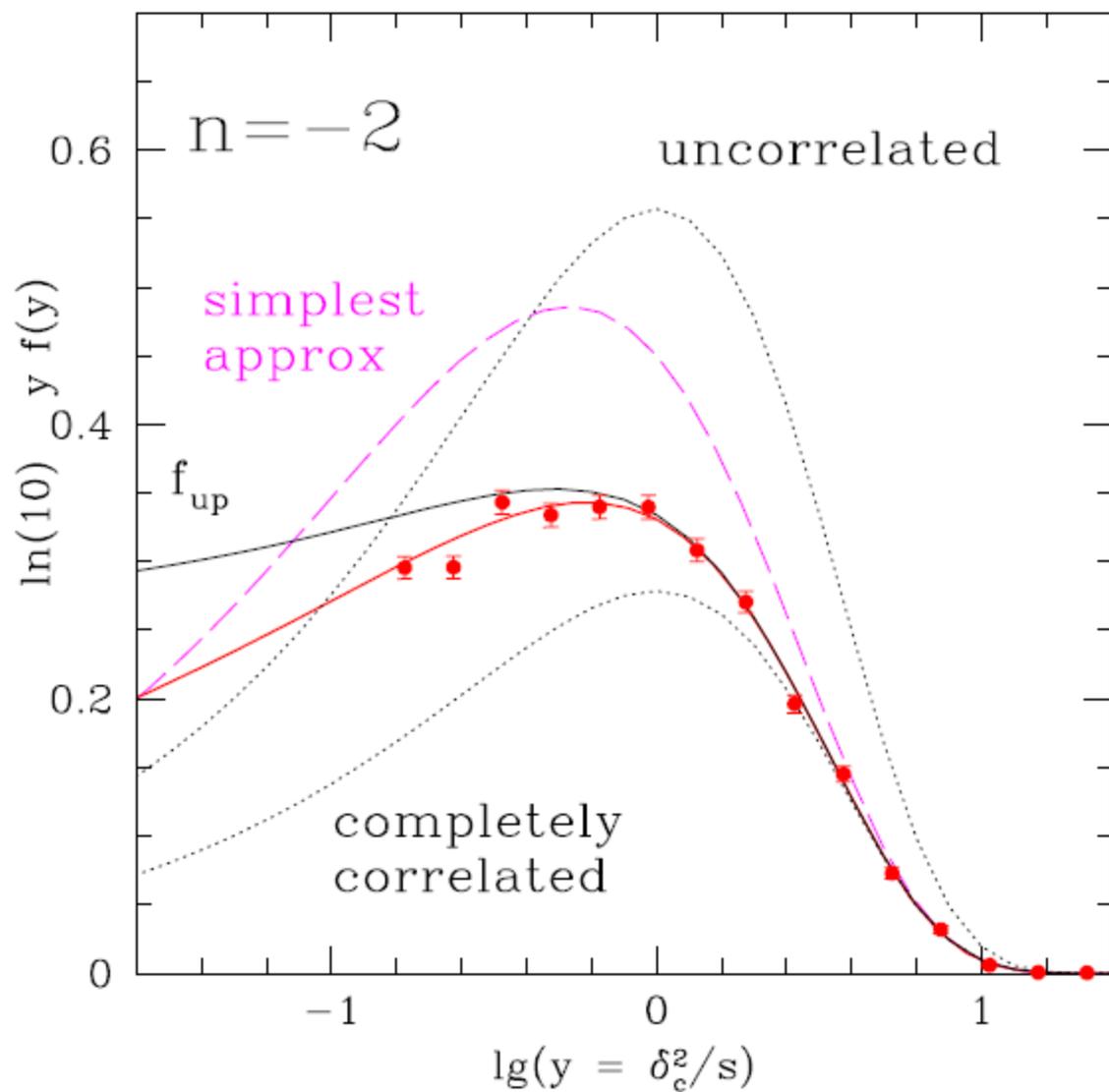
N.B. Not quite universal because of Γ :

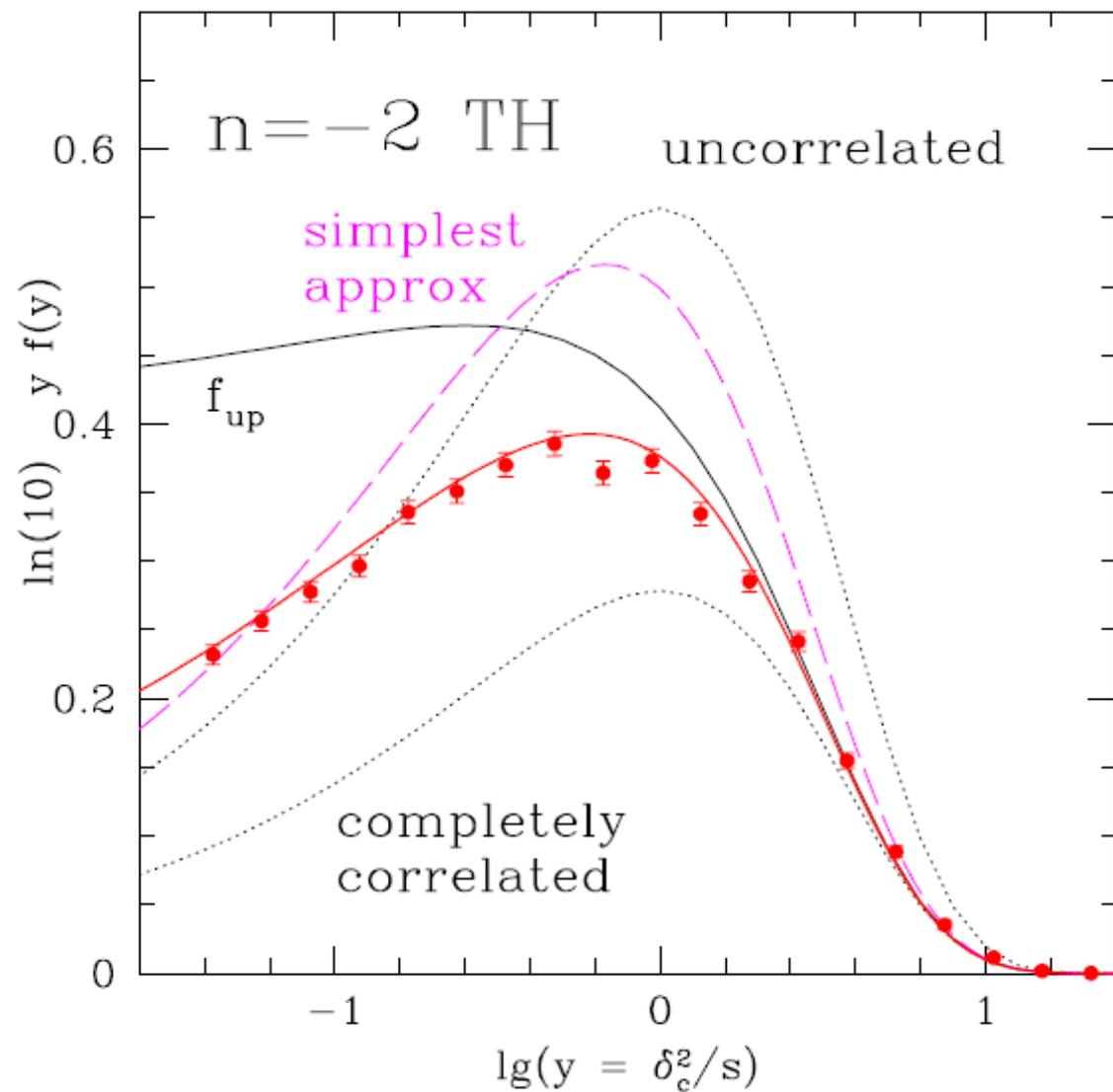
$$\gamma^2 \equiv \frac{\langle \delta\delta' \rangle^2}{\langle \delta^2 \rangle \langle \delta'^2 \rangle} \quad \text{and} \quad \Gamma^2 = \frac{\gamma^2}{1 - \gamma^2}$$







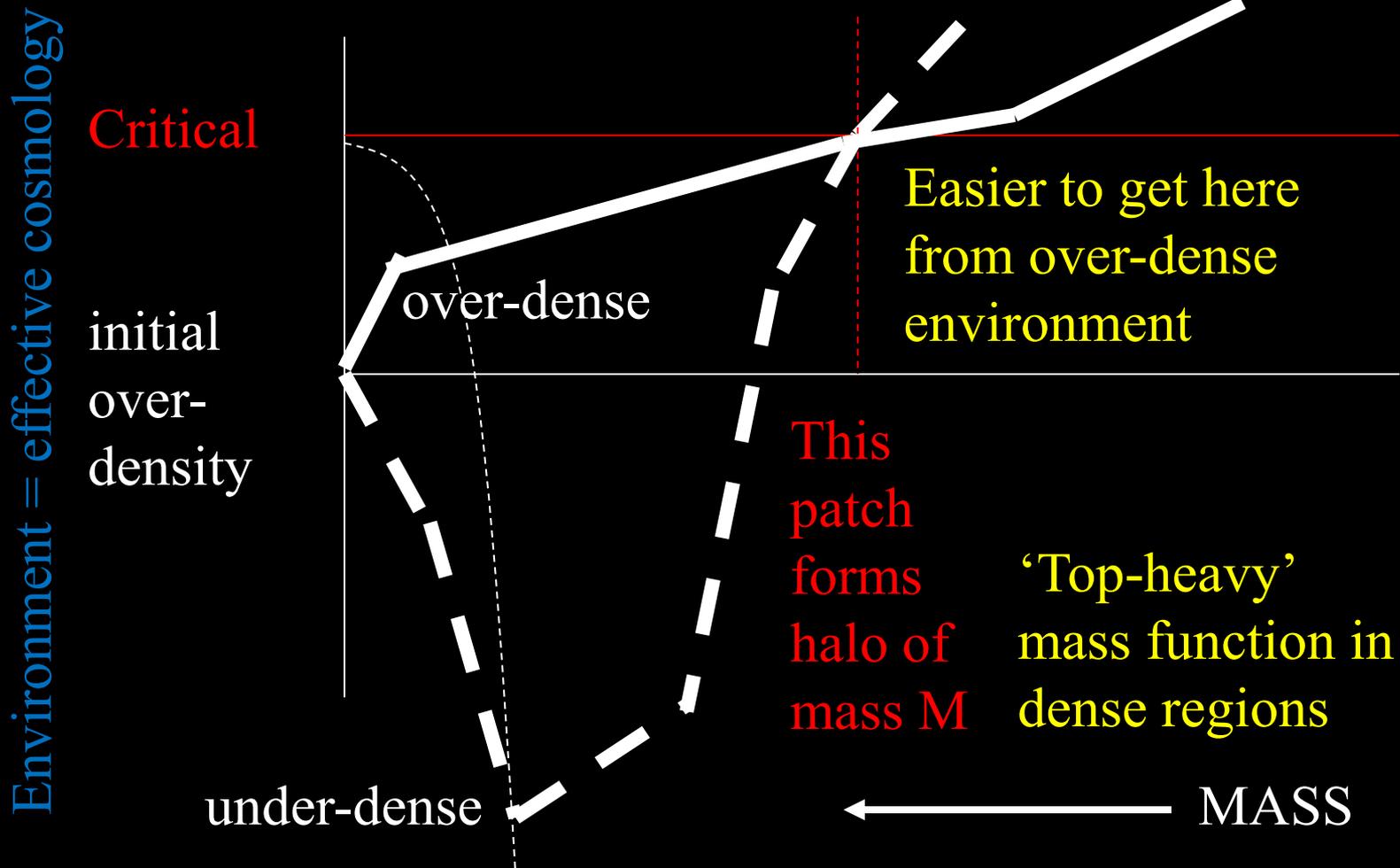




The first crossing distribution,
for arbitrary barriers and arbitrary
correlation structures,
is now a solved problem.

(Musso & Sheth 2014)

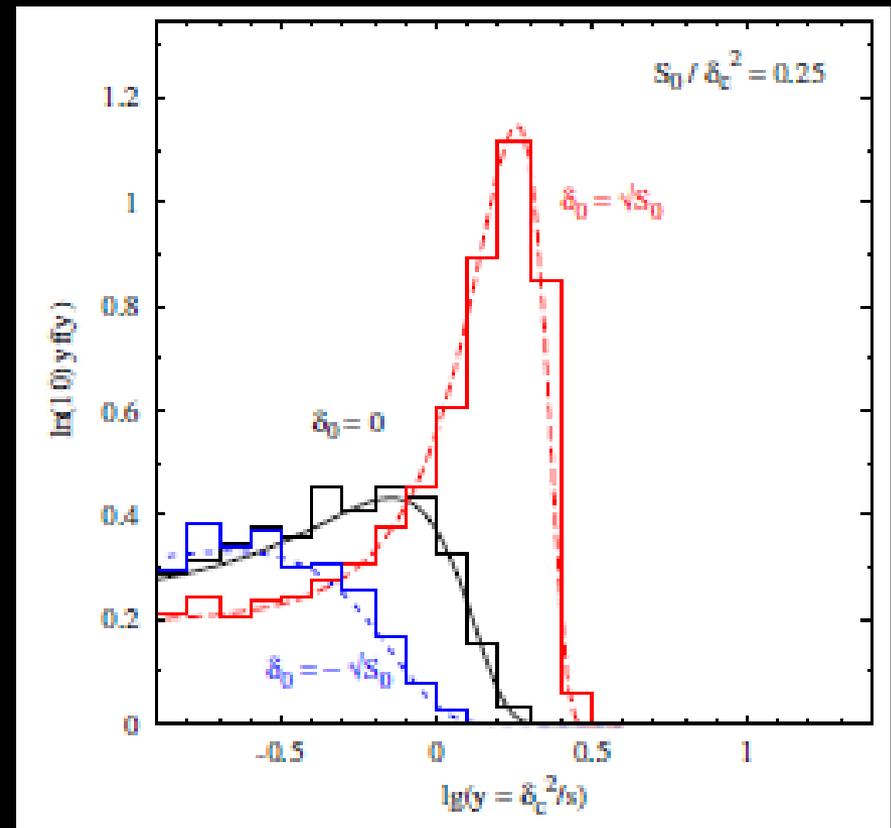
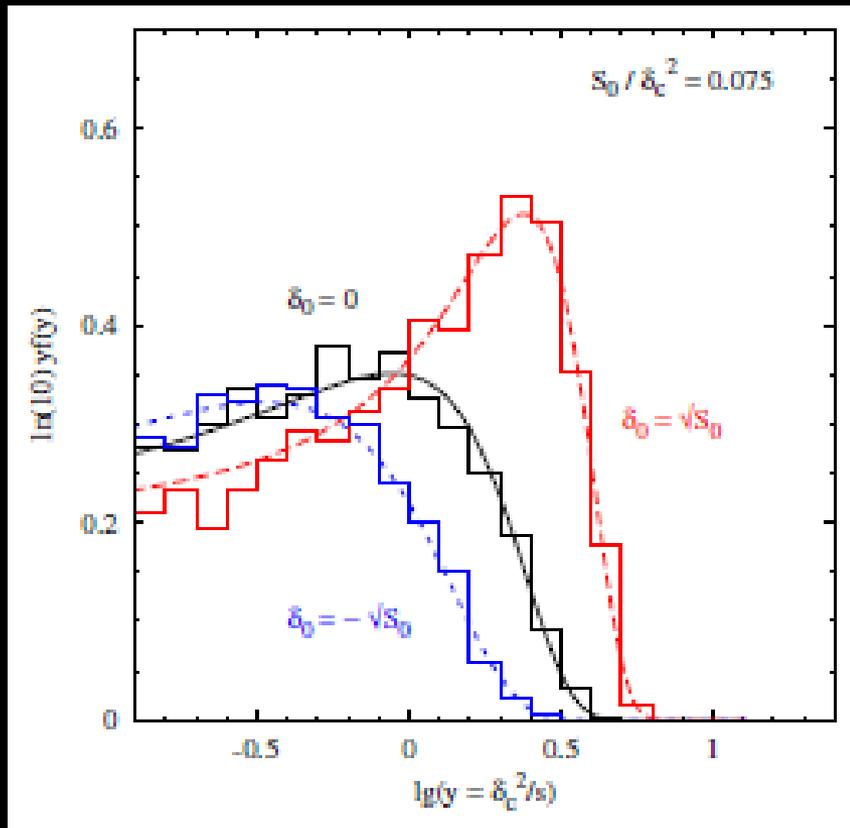
Correlations with environment



Constrained walks with correlated steps easy:

$$\begin{aligned} f(s|\delta_0, \mathbf{S}) ds &\approx \int dv \int d\delta \ p(\delta, v|\delta_0) \\ \text{over } \delta_c < \delta < \delta_c + \Delta s \ v \ \text{and } v > 0 \\ &= \Delta s \ p(\delta_c|\delta_0) \int dv \ p(v|\delta_c, \delta_0) \ v \\ &= \Delta s \ p(\delta_c|\delta_0) \ \langle v|\delta_c, \delta_0 \rangle \end{aligned}$$

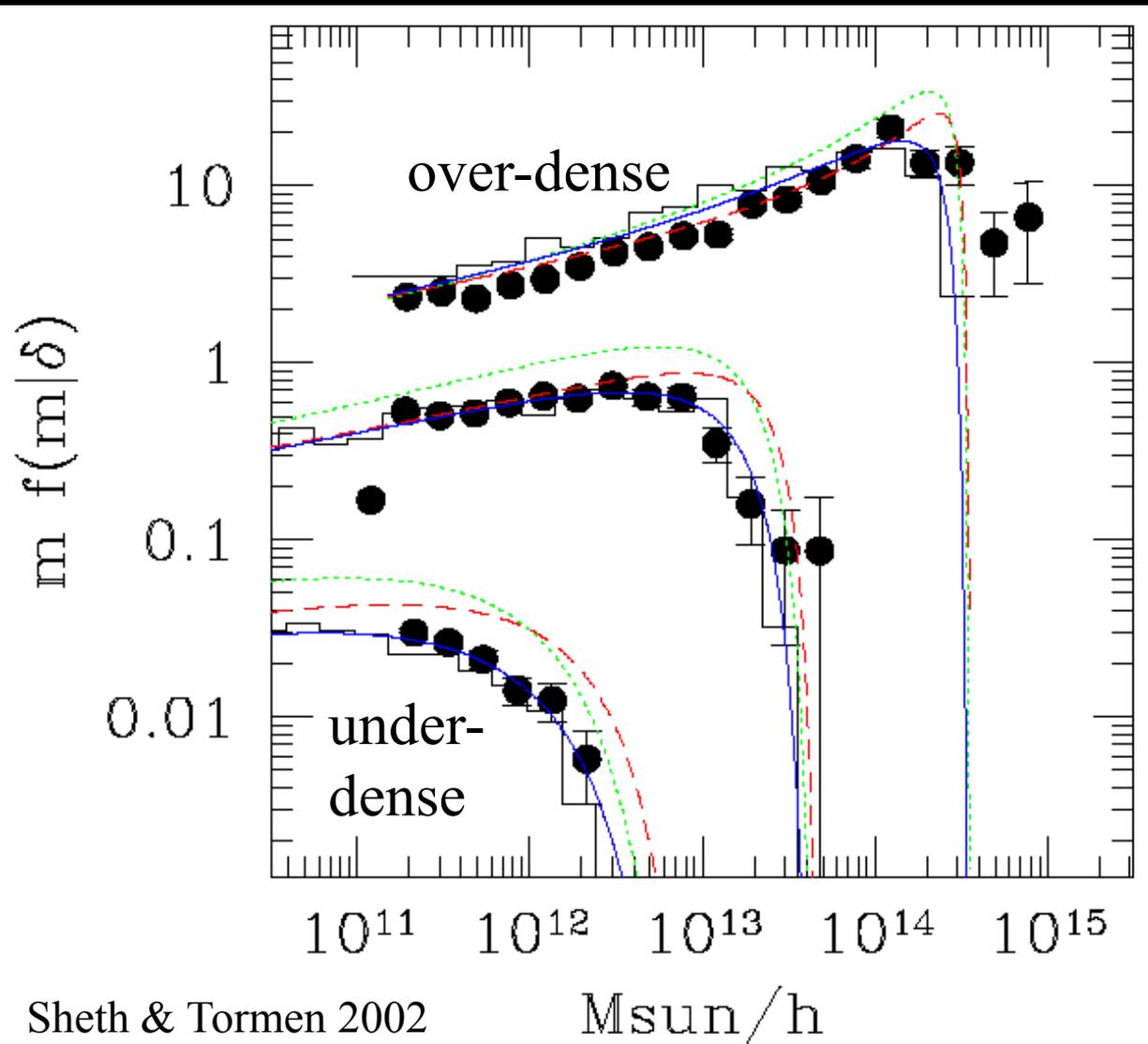
Constrained walks easy ...



... and accurate (Musso, Paranjape, Sheth 2012)

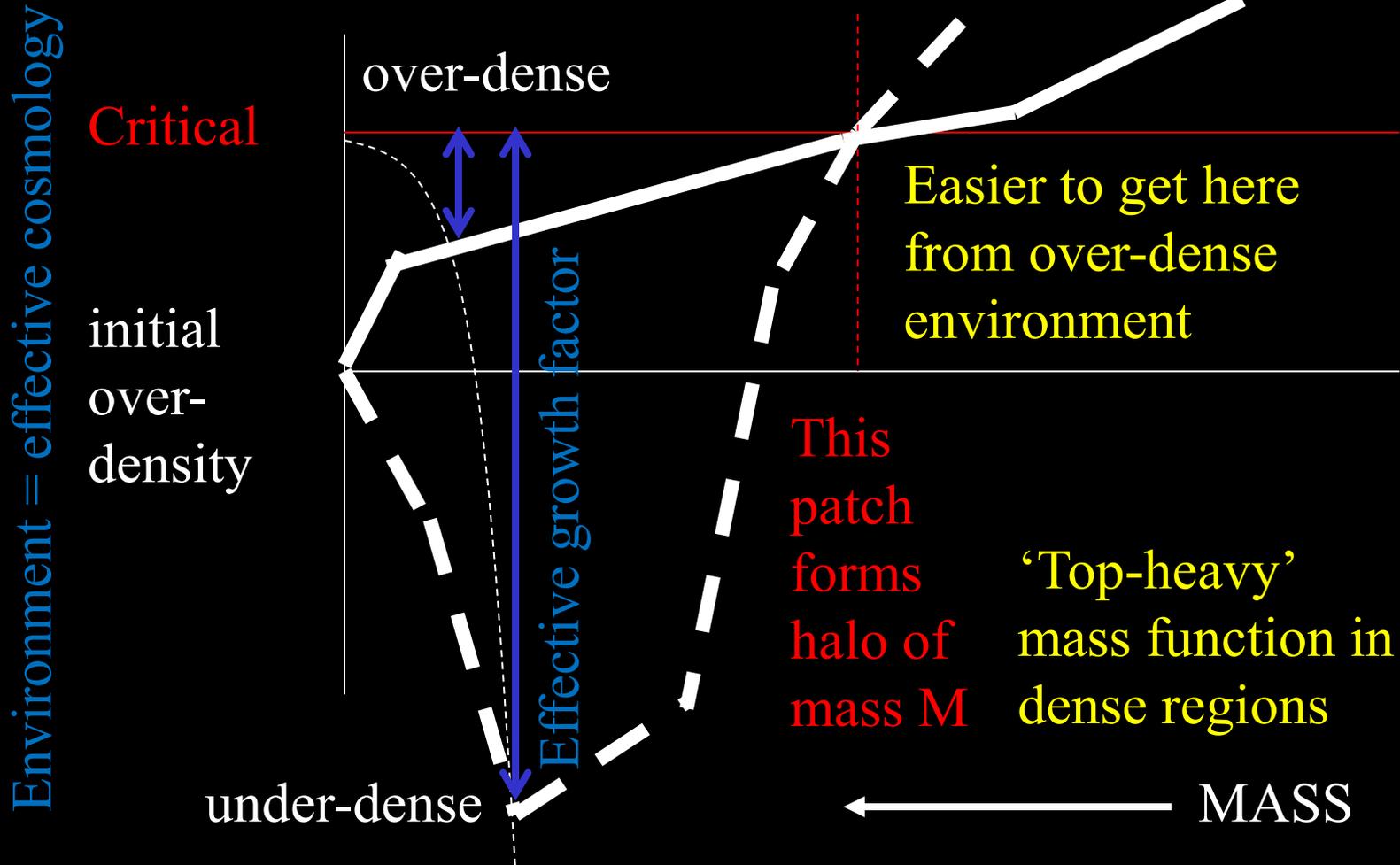
Most
massive
halos
populate
densest
regions

Key to understand
galaxy biasing



$$n(m|\delta) = [1 + \mathbf{b(m)\delta}] n(m) \neq [1 + \delta] n(m)$$

Correlations with environment



On the equivalence between the effective cosmology and excursion set treatments of environment

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ABSTRACT

In studies of the environmental dependence of structure formation, the large-scale environment is often thought of as providing an effective background cosmology: for example the formation of structure in voids is expected to be just like that in a less dense universe with appropriately modified Hubble and cosmological constants. However, in the excursion set description of structure formation which is commonly used to model this effect, no explicit mention is made of the effective cosmology. Rather, this approach uses the spherical evolution model to compute an effective linear theory growth factor, which is then used to predict the growth and evolution of non-linear structures. We show that these approaches are, in fact, equivalent: a consequence of Birkhoff's theorem. We speculate that this equivalence will not survive in models where the gravitational force law is modified from an inverse square, potentially making the environmental dependence of clustering a good test of such models.

Key words: methods: analytical – dark matter – large-scale structure of Universe.

Environmental effects

- In hierarchical models, close connection between evolution and environment (dense region \sim dense universe \sim more evolved)
- Astrophysics determined by formation history of halo
- Observed correlations with environment test hierarchical galaxy formation models – all environmental effects because massive halos populate densest regions

Large scale bias coefficients from
Taylor series around δ_0

$$f(s|\delta_0, \mathbf{S}) = p(\delta_c|\delta_0) \langle v|\delta_c, \delta_0 \rangle$$

Bias gets additional contribution
from dependence of mean v on
large scale δ_0

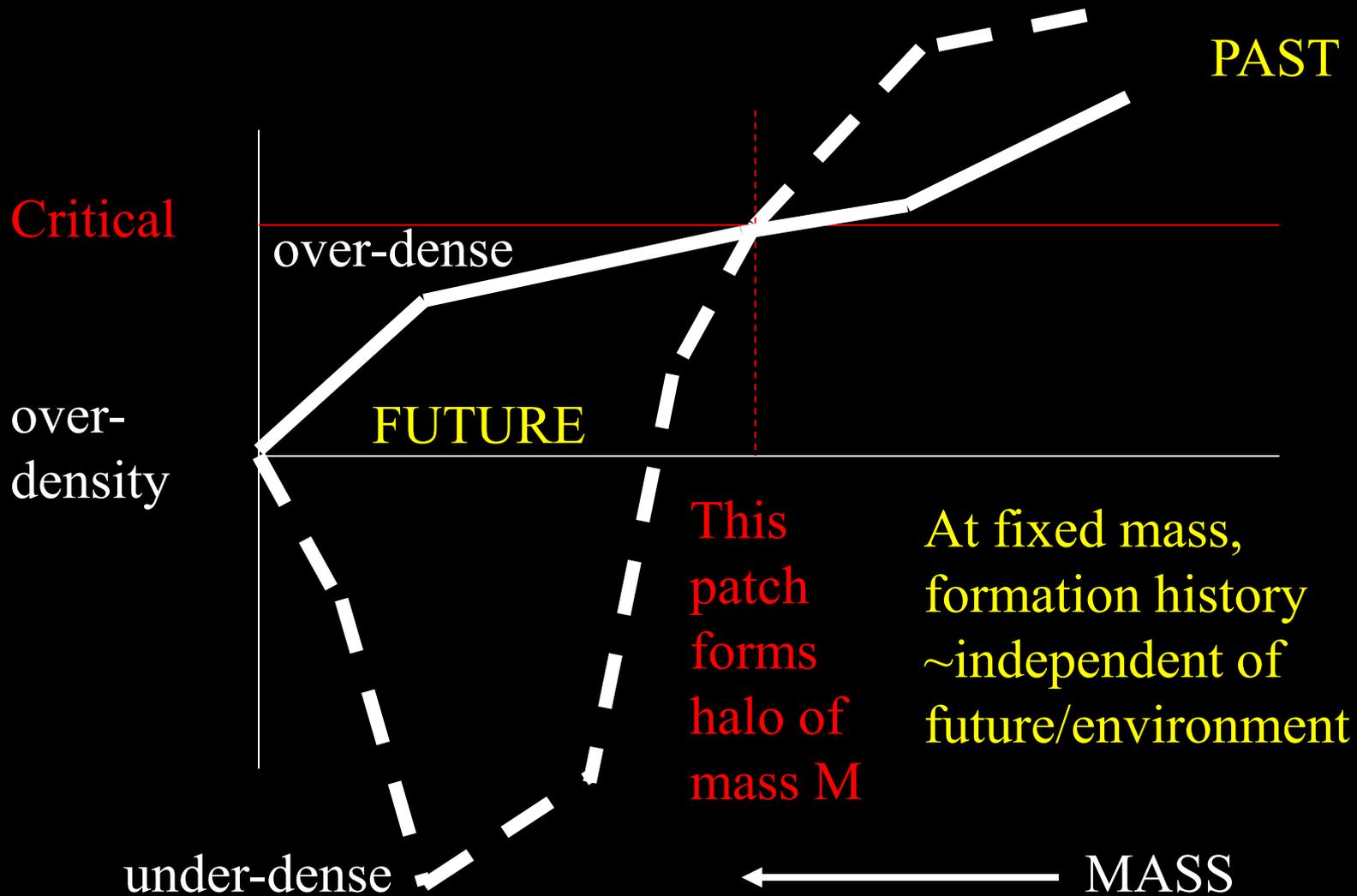
- Dependence on v makes bias factor k -dependent, because v means derivative with respect to smoothing filter; e.g. $W = \exp(-k^2 R^2/2)$:

$$\text{bias}(k) = (b_{10} + b_{01} k^2)W(kR_h)$$

This is generic.

- Coefficients depend on halo mass; there are consistency relations between coefficients

Correlations with environment



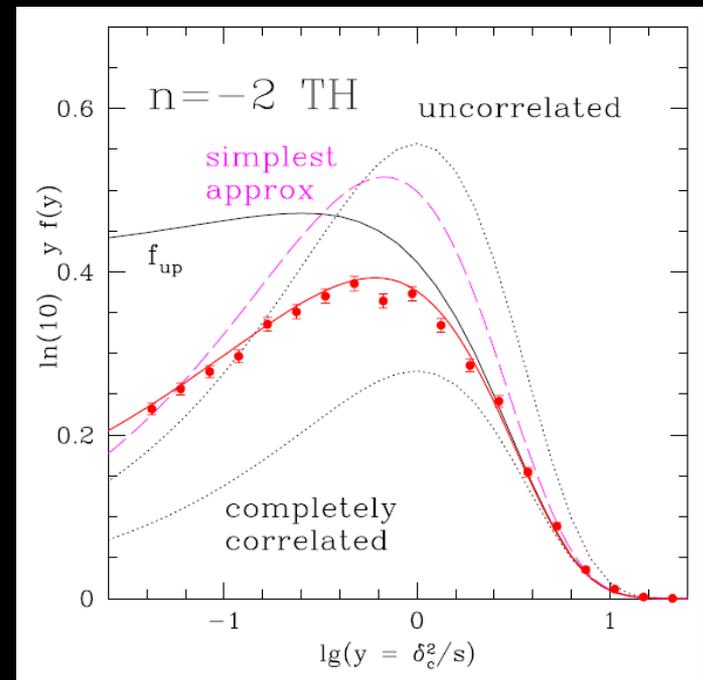
Assembly bias

- At fixed mass, formation history independent of future/environment *if walks are Markovian* i.e. have uncorrelated steps (White 1996)
- In simulations, at fixed mass, formation history *does* correlate with environment (Sheth & Tormen 2004; Gao et al. 2005; etc.)
- A simple ‘Markov Velocities’ model captures most of this effect (Musso & Sheth 2014)

Markov Velocities ...

- (Old) independent steps
= Markov heights

$$p(\delta|\Delta, \Delta, \Delta, \dots) = p(\delta|\Delta)$$



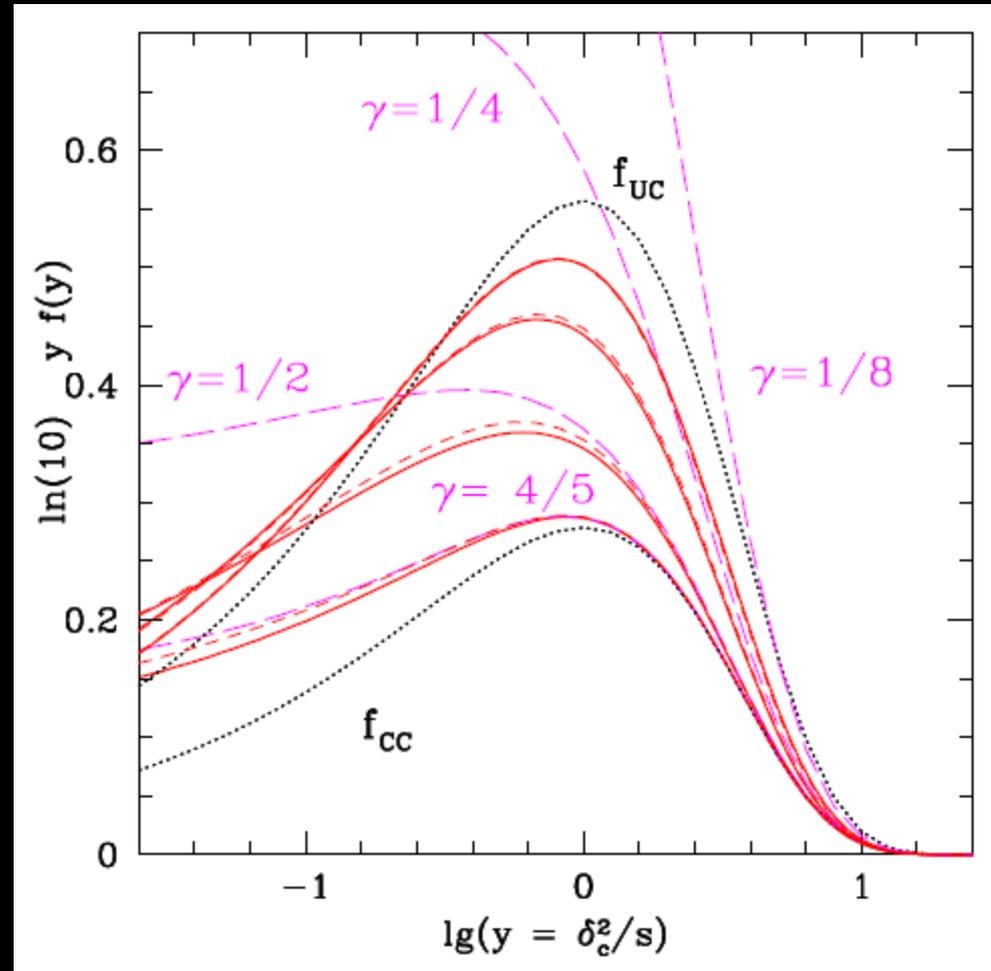
- (New) Markov velocities = correlated steps but

$$p(\delta|\Delta, \Delta, \Delta, \dots) = p(\delta|\Delta, \Delta')$$
 and similarly

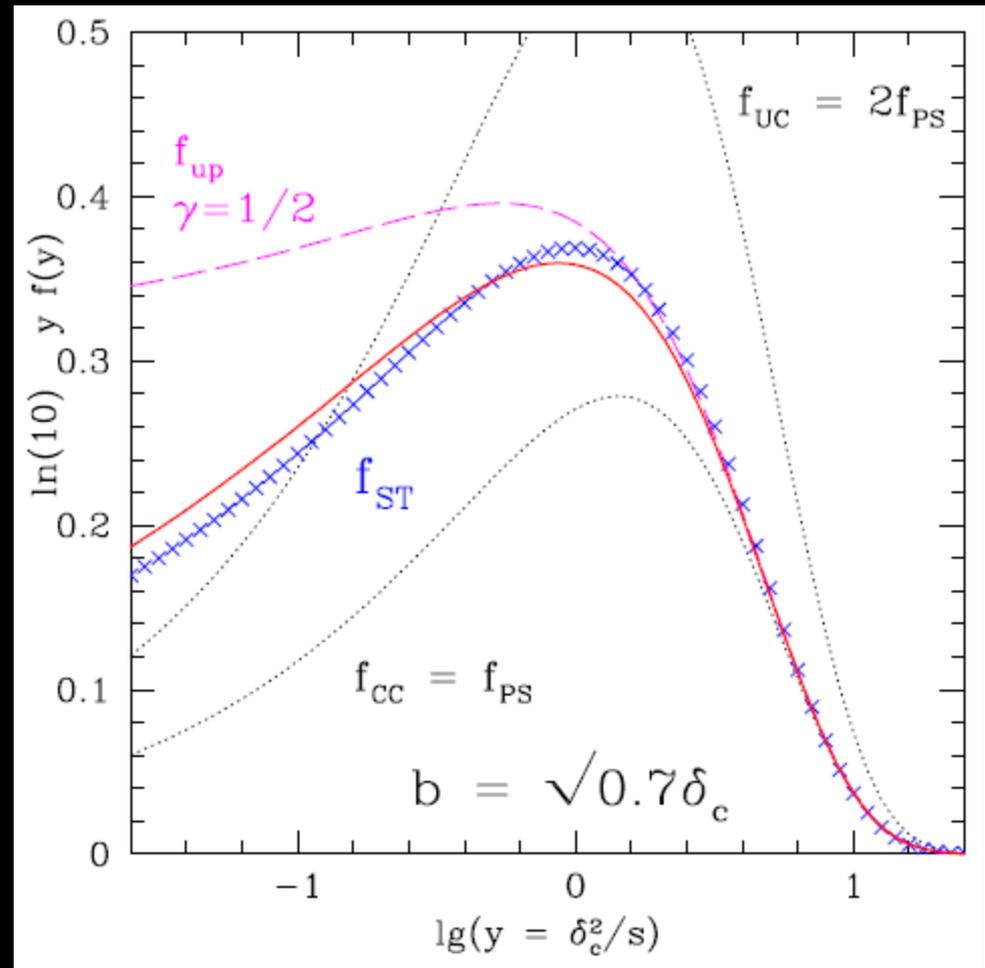
$$p(\Delta|\delta, \delta', \delta, \delta', \delta, \delta', \dots) = p(\Delta|\delta, \delta')$$

... have simplest realistic Assembly Bias built-in

Large family
of models
with different
correlation
structures



Can provide
good description
of formulae
used to fit halo
counts in
simulations,
provided ...

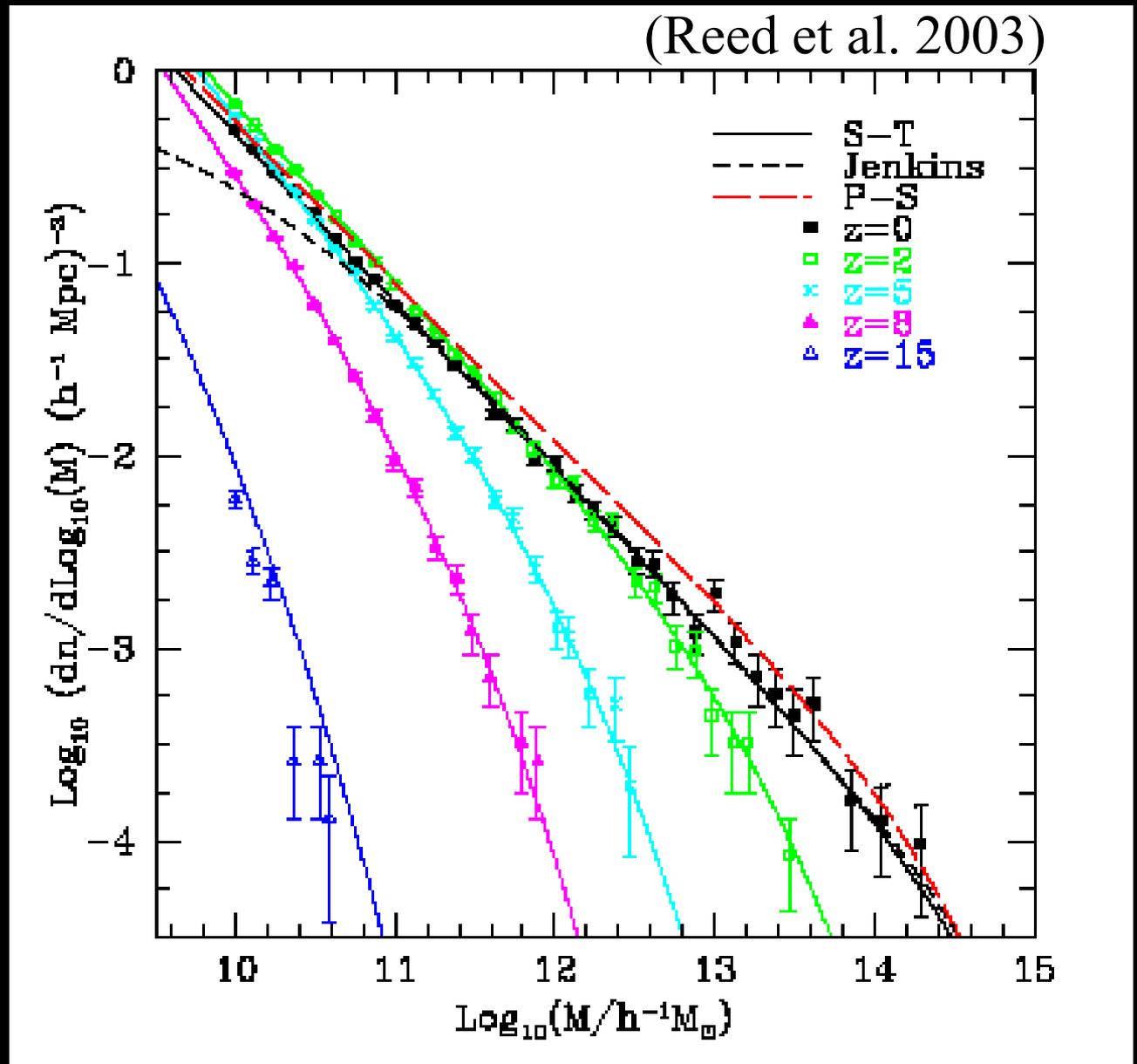


From walks to halos ...

- Use first crossing distribution as physically motivated fitting formula in terms of $a v$ and fit for a
- I.e., find that a for which
$$f(v)dv = f(m,z)dm = (m/\rho) dn(m,z)/dm dm$$
where dn/dm is comoving number density of halos of mass m at z
- It happens that $a \sim 0.85$ approximately independent of cosmology and z

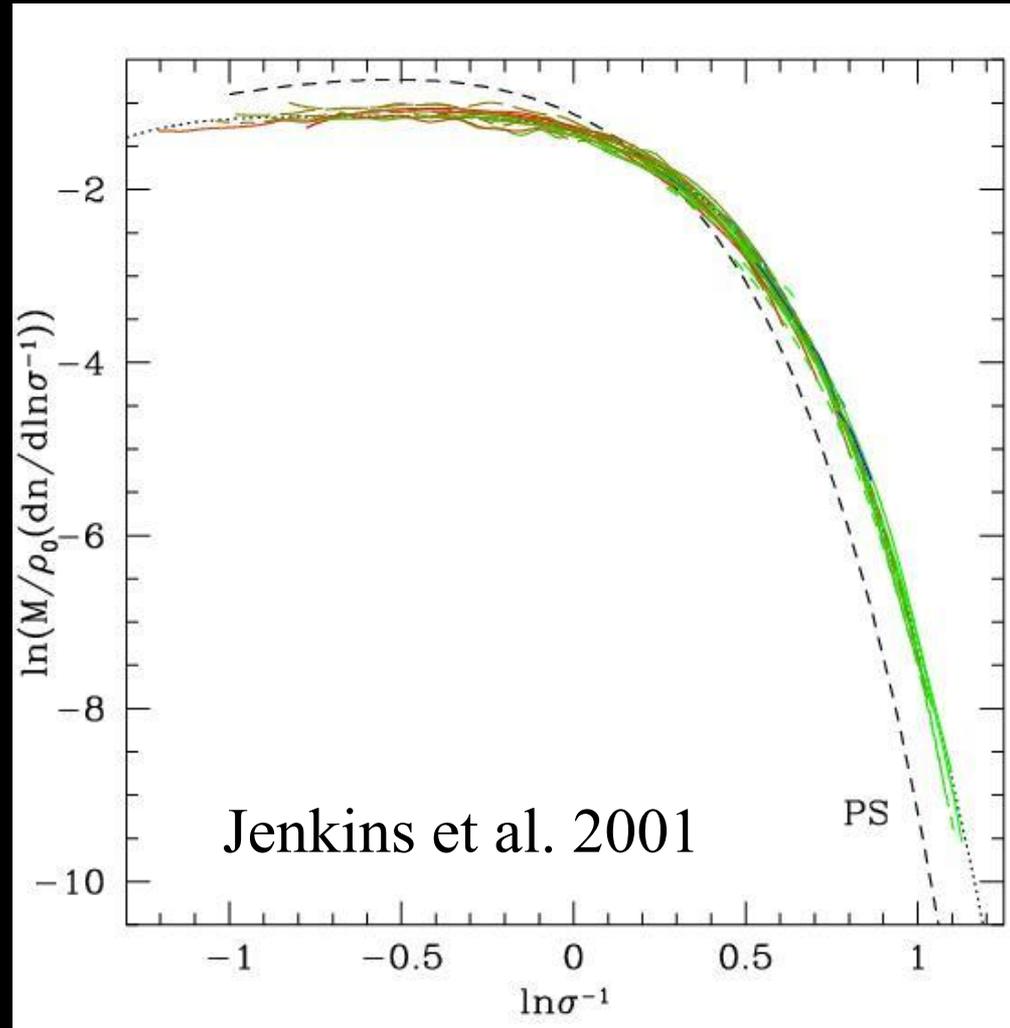
The Halo Mass Function

- Small halos collapse/virialize first
- Can also model halo spatial distribution
- Massive halos more strongly clustered



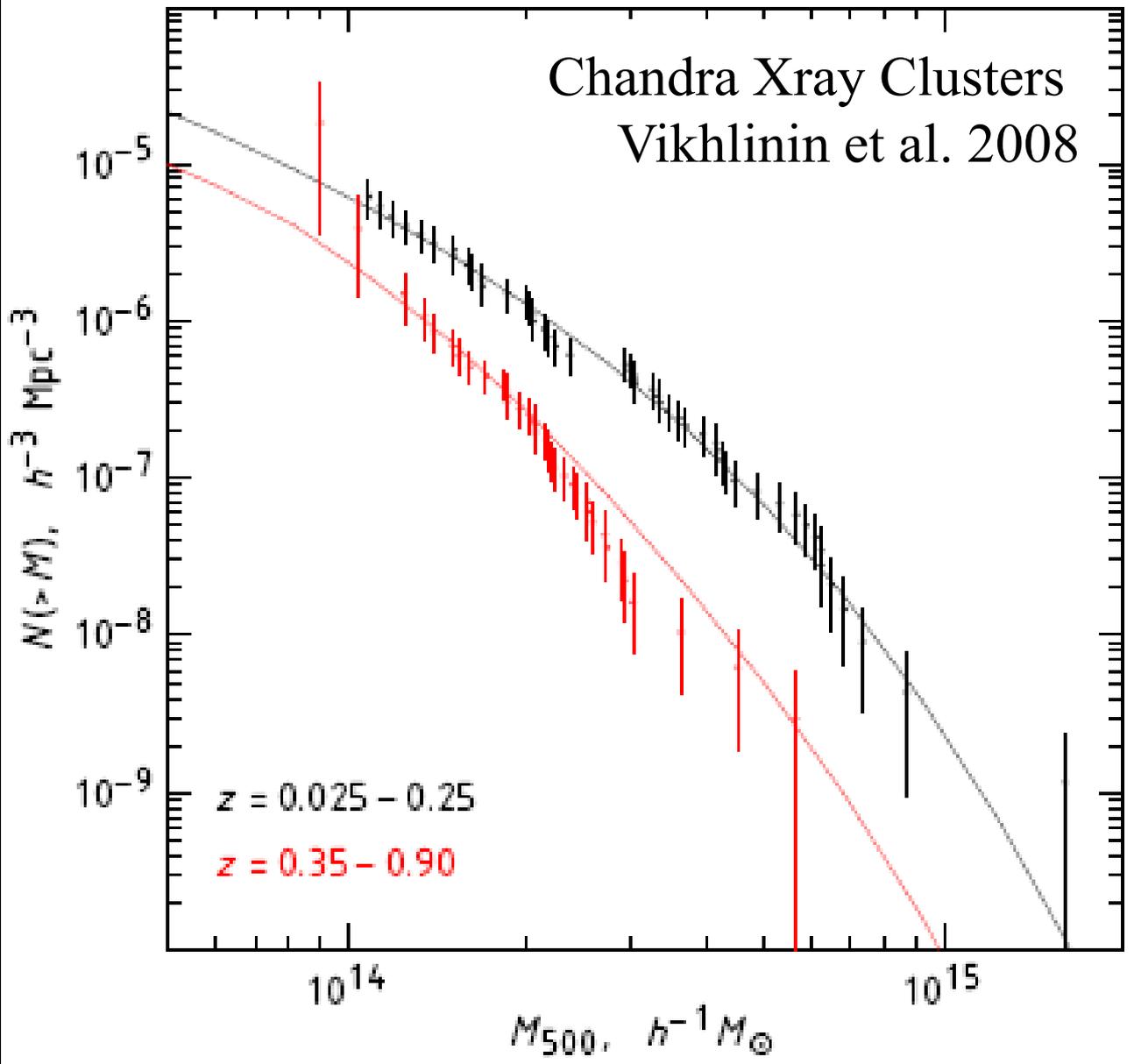
Universal form?

- Spherical evolution
(Press & Schechter 1974;
Bond et al. 1991)
- Ellipsoidal evolution
(Sheth & Tormen 1999;
Sheth, Mo & Tormen
2001)
- Simplifies analysis of
cluster abundances
(e.g. X-ray, SZ, Opt)
- Small departures from
universality now seen

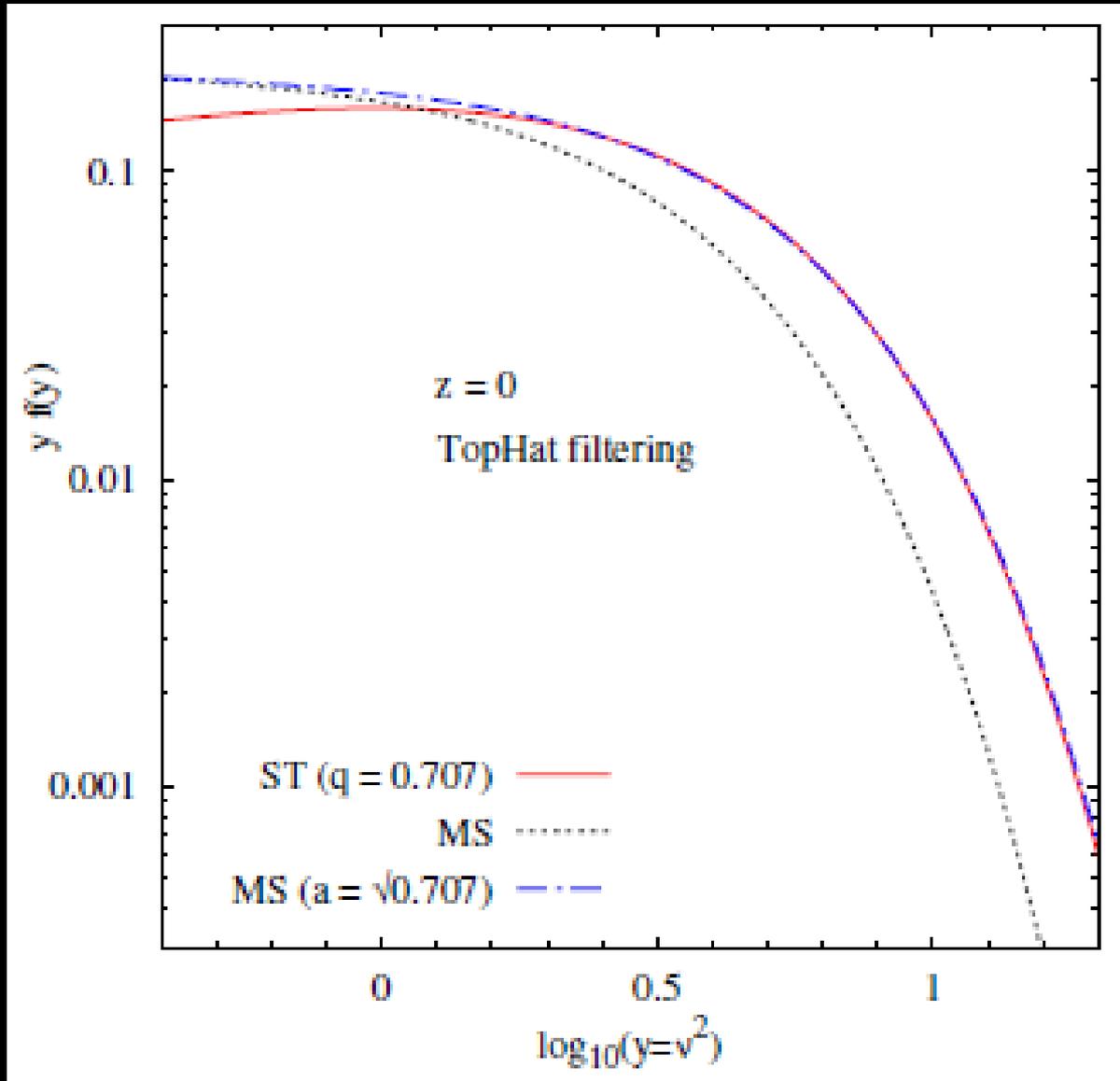


Chandra Xray Clusters

Vikhlinin et al. 2008



Yet another stretch factor in cosmology?



The real
cloud-in-cloud problem:

When spheres are no
longer concentric

In concentric spheres problem progress
from thinking of nearby scales, and so
derivatives with respect to scale

For non-concentric spheres, think of next
nearby position: taking derivatives wrt
position leads to ... Peaks Theory

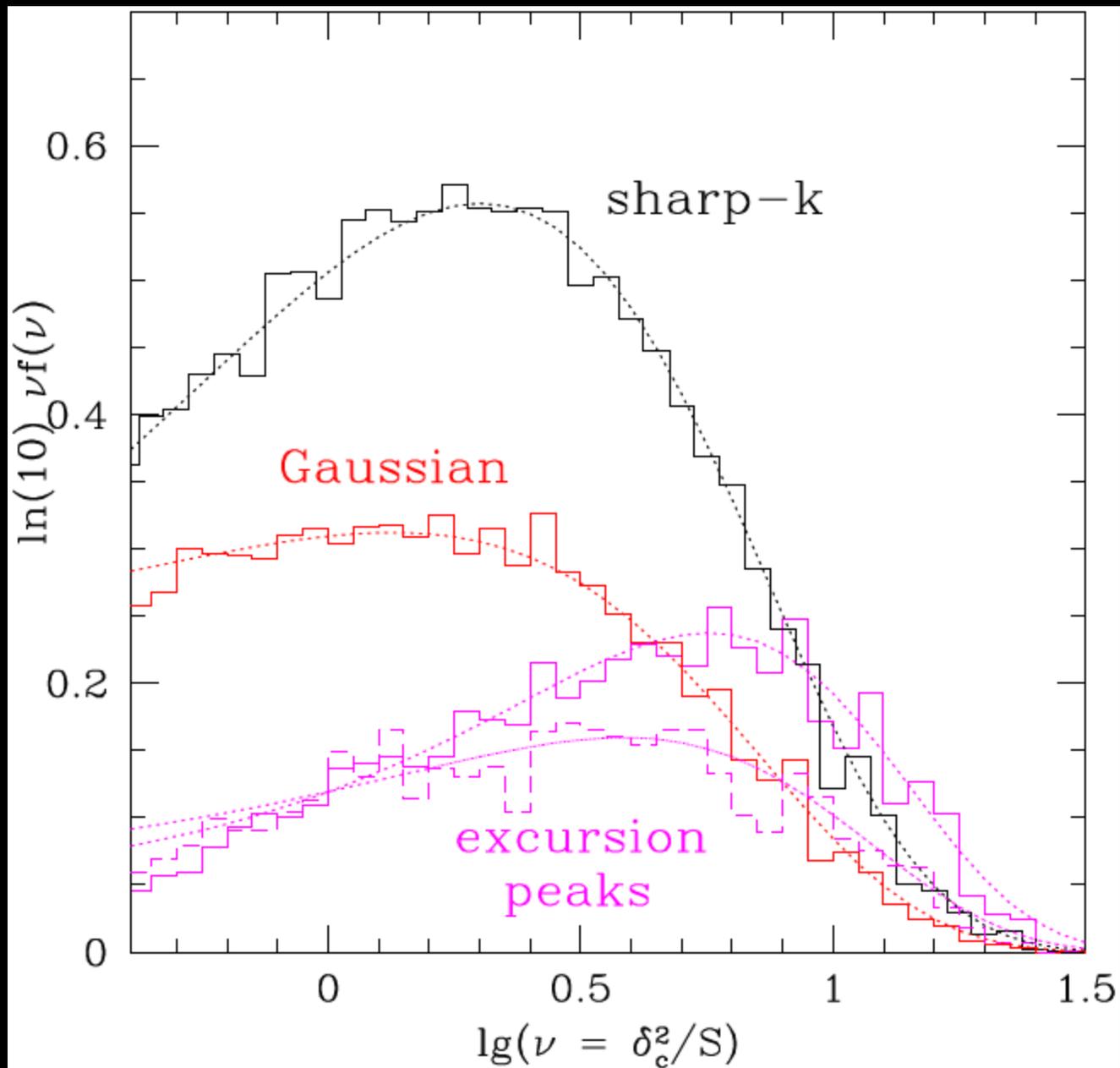
Resulting Excursion Set Peaks
model is marriage of two 20 yr old
literature streams

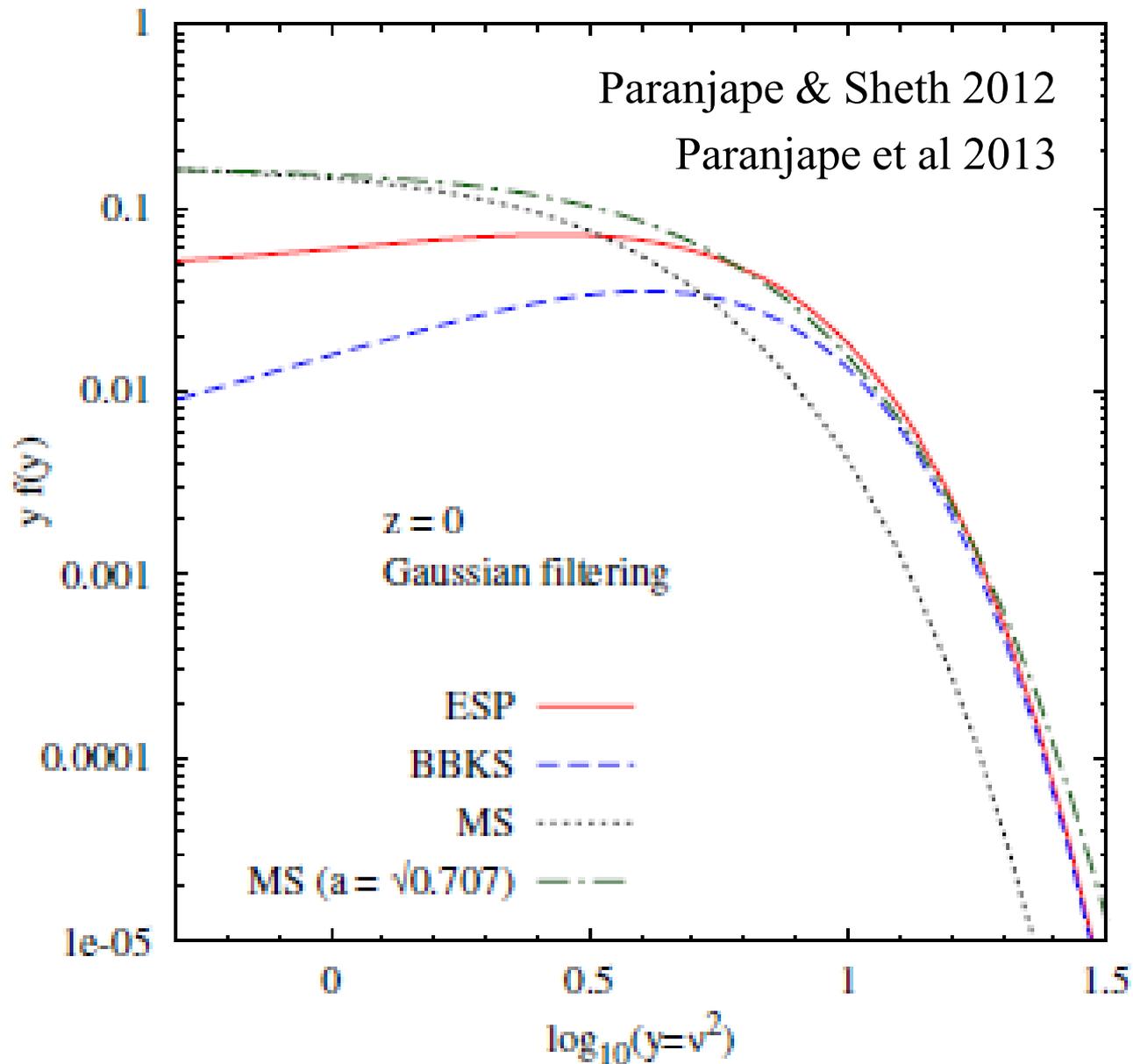
Excursion set peaks

$$\begin{aligned} f(s|\text{peak})ds &\approx \int dv \int d\delta \ p(\delta, v) \ q_{\text{peak}}(v) \\ &\text{over } \delta_c < \delta < \delta_c + \Delta s \ v \ \text{and} \ v > 0 \\ &= \Delta s \ p(\delta_c, s) \int dv \ p(v | \delta_c) \ q_{\text{peak}}(v) \ v \\ &= \Delta s \ p(\delta_c, s) \langle v | \delta_c, \text{peak} \rangle \end{aligned}$$

Correlated walks? No.

Better choice of ensemble over
which to average? Yes.



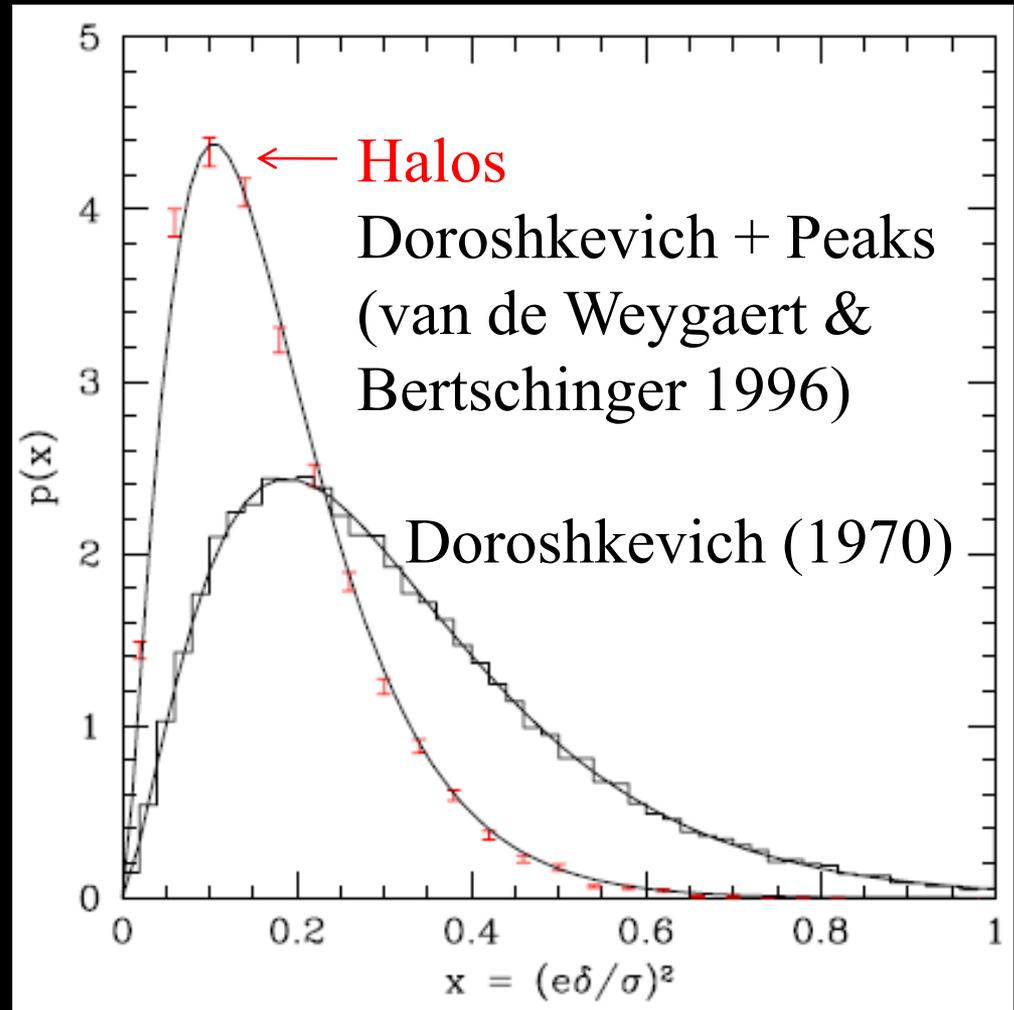


More direct evidence from statistics of initial patches

- For EC, need $p(\delta, e, p) = p(\delta) p(e, p | \delta)$
- For random patches, Doroshkevich (1970) shows $p(e, p | \delta)$ same for all δ , and distribution of $(\delta e) / \sigma(m) \sim (\lambda_1 - \lambda_3) / \sigma(m)$ is universal
- In simulations, $p(\delta e / \sigma)$ indeed universal, but with smaller variance \sim like distribution around peaks in δ .

Essentially all previous analyses averaged over an ensemble of randomly placed walks.

Therefore they implicitly assumed that the statistics of center-of-mass walks are the same as those in random positions. This is wrong (Sheth, Mo, Tormen 2001).



Despali, Tormen, Sheth 2013

Recall: Large scale bias from
Taylor series around δ_0 ;
Bias gets additional contribution
from dependence of mean v on
large scale δ_0 :

$$f(s|\delta_0, \mathbf{S}) = p(\delta_c|\delta_0) \langle v|\delta_c, \delta_0 \rangle$$

- Dependence on v makes bias factor k -dependent:

$$\text{bias}(k) = (b_{10} + b_{01} k^2) W(kR_h)$$

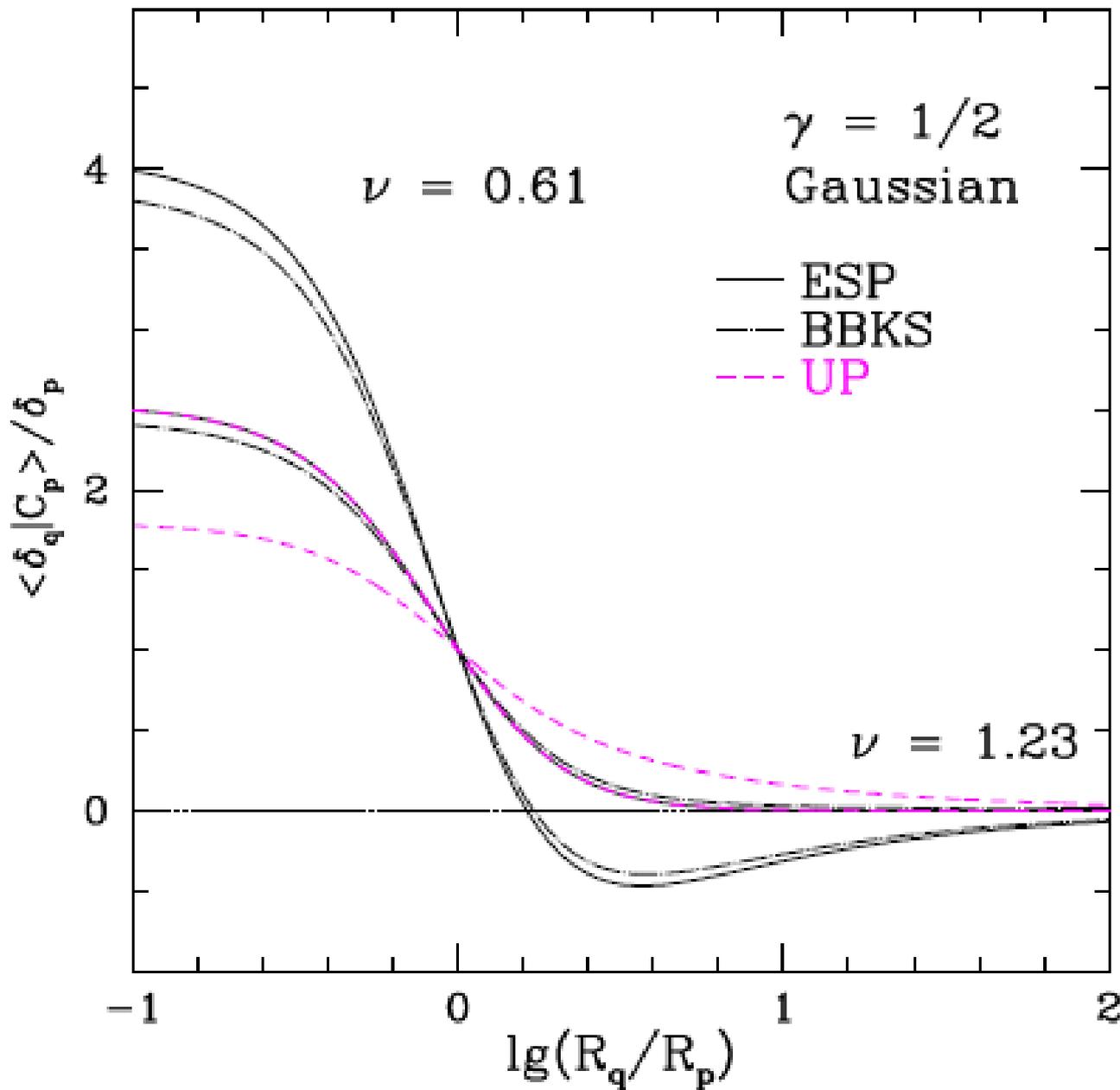
This is generic

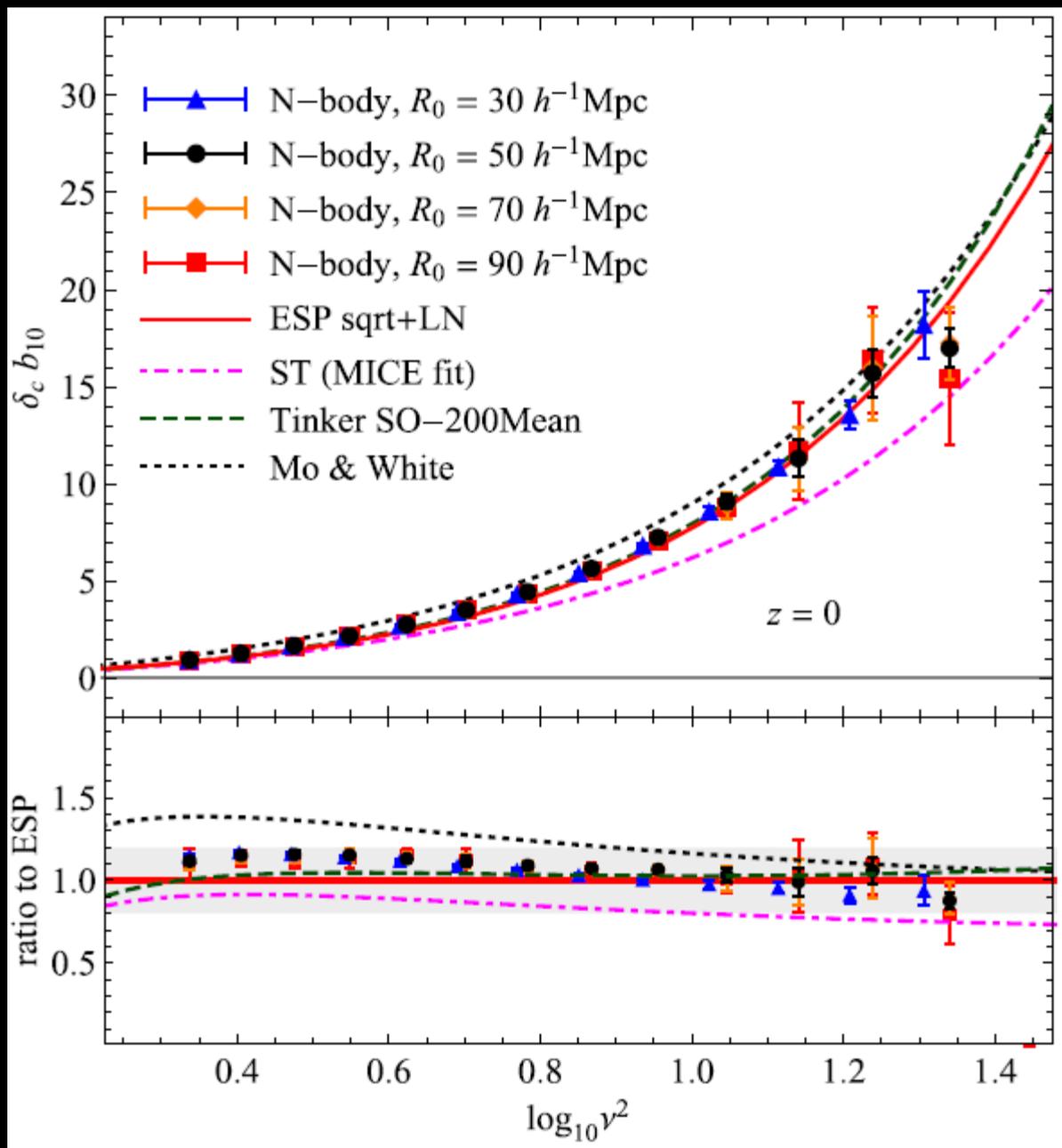
- Coefficients depend on halo mass
- Since peaks have different v 's but otherwise same structure, peak bias has same structure but different coefficients

Density
profile =

cross
correlation
between peak
and mass

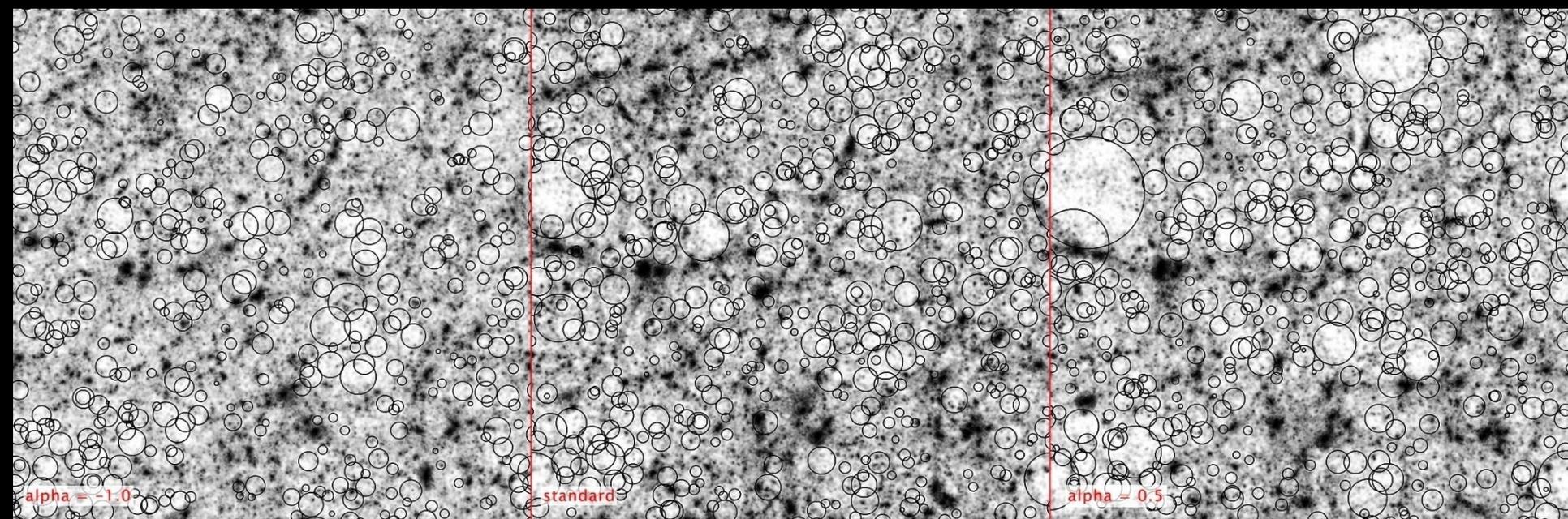
Generic:
Low mass =
more
concentrated





'Modified' gravity theories

Martino & Sheth 2009



weaker gravity

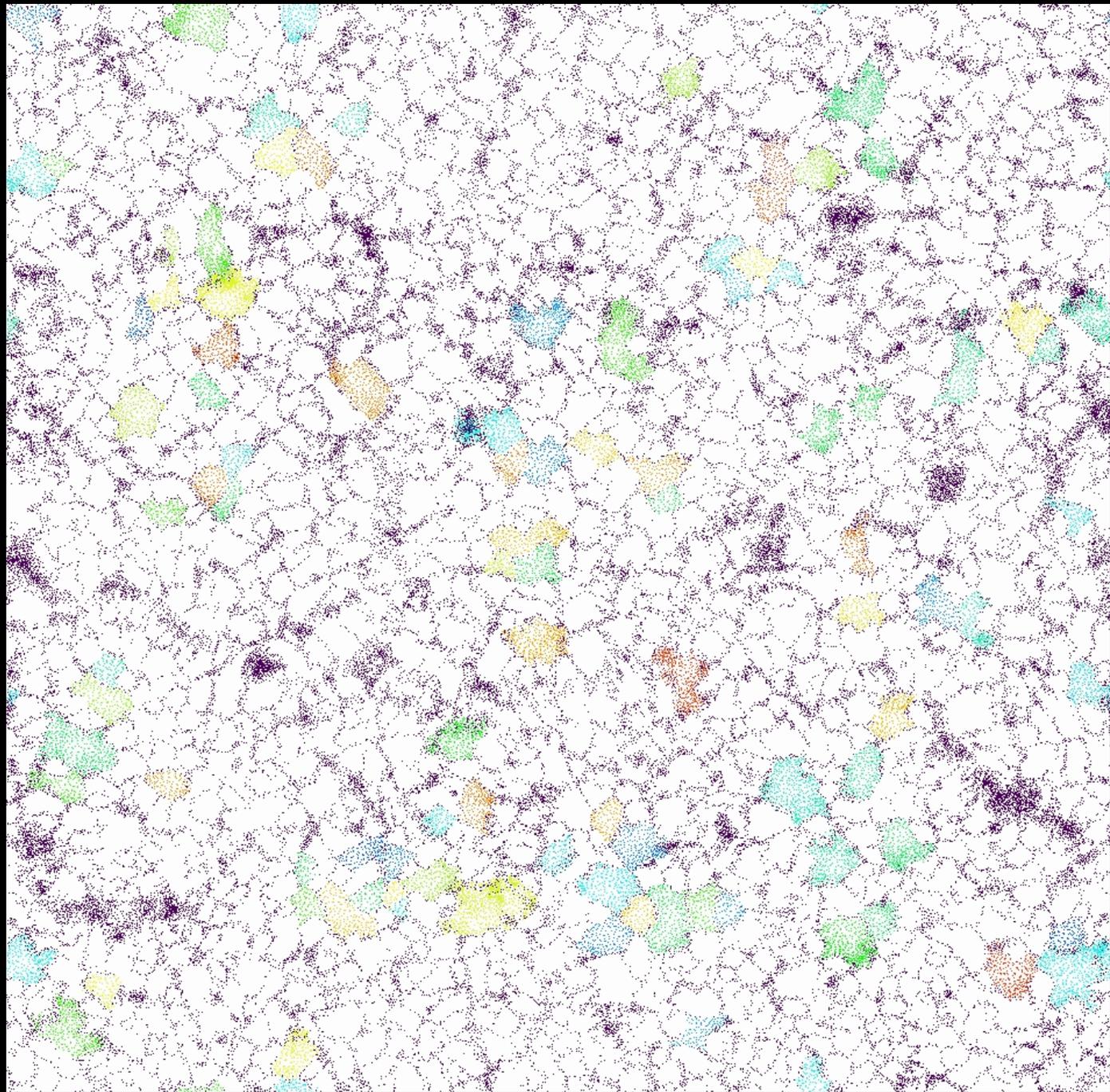
on large scales

stronger gravity

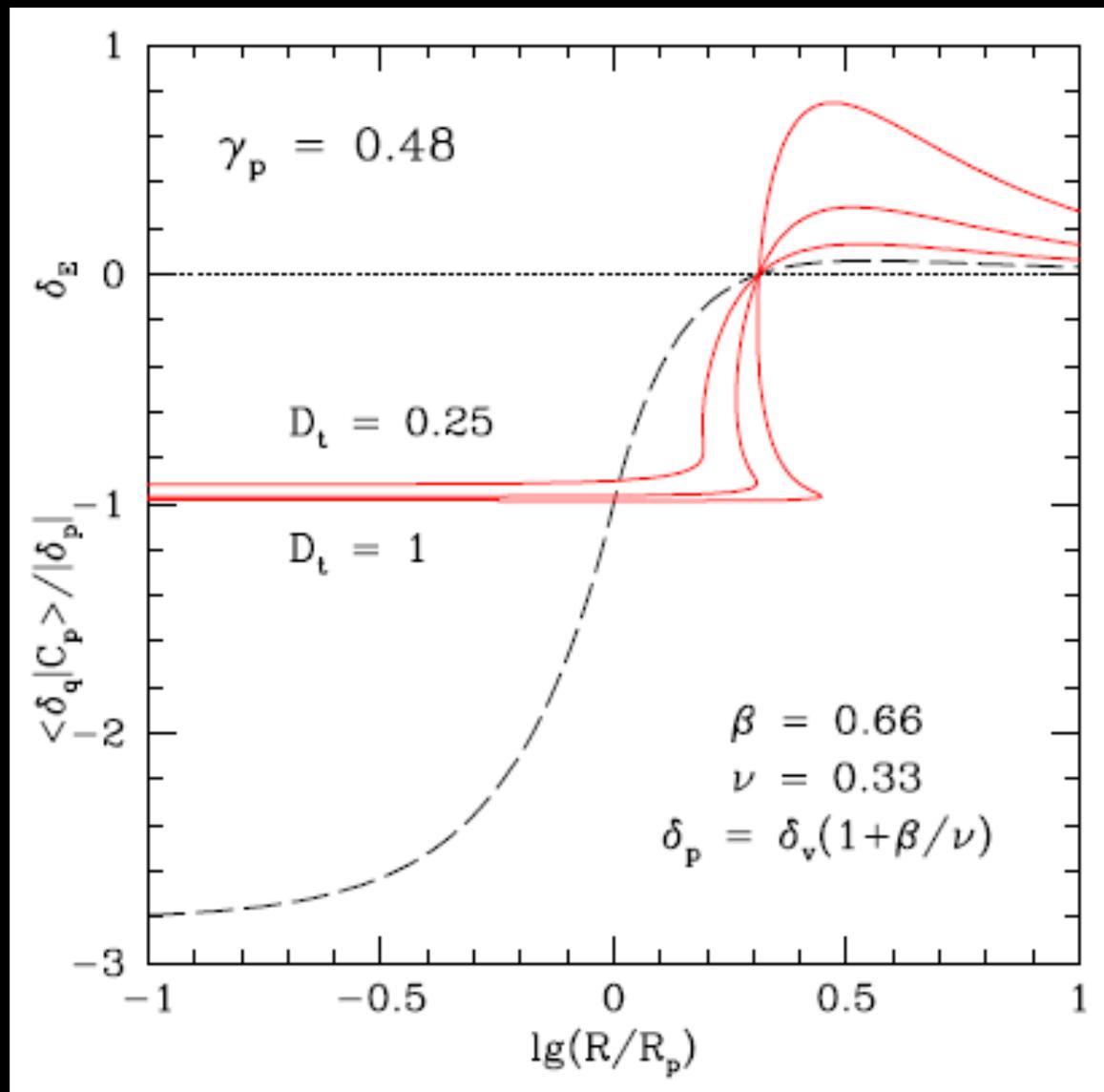
Voids/clusters/clustering are useful indicators

Voids

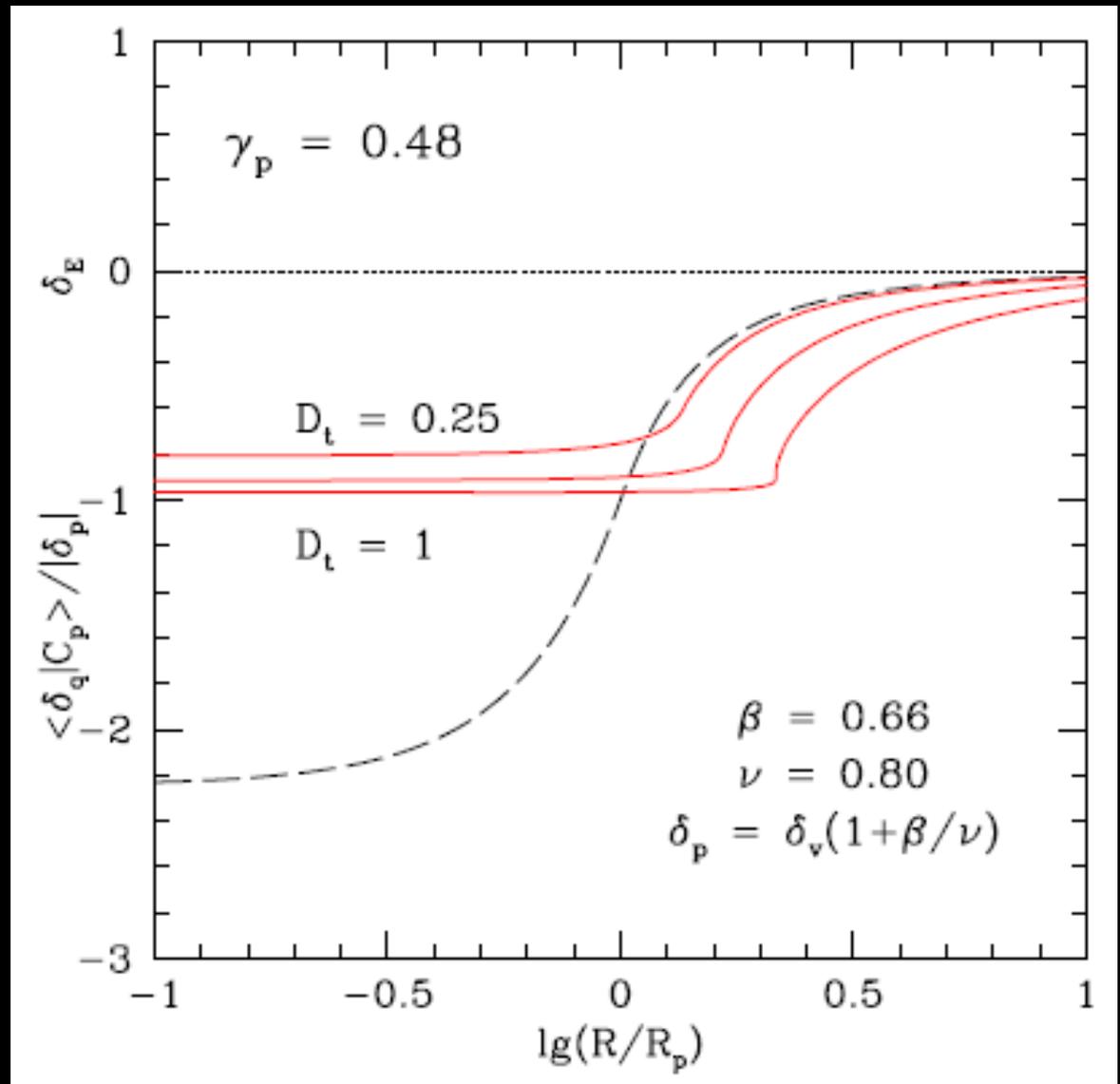
- Just change sign, so can do almost same cosmology with voids as with clusters
- Must be a little careful since small voids can be crushed if surroundings sufficiently overdense (Sheth, van de Weygaert 2004)
- Change of sign interesting because
 $b^E = 1 + b^L$ can equal zero for certain voids
whereas $b^E > 0$ for halos.



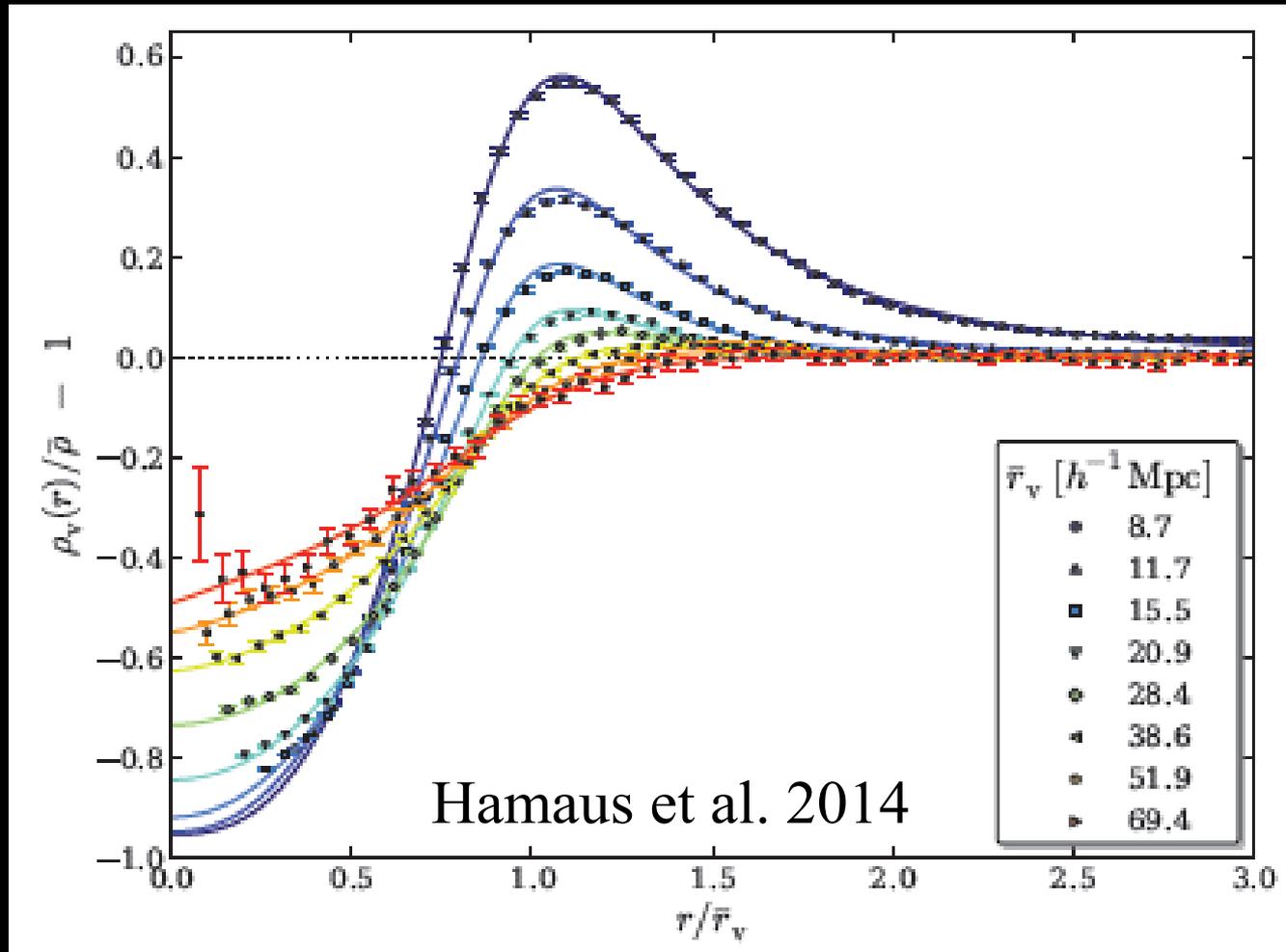
Small
voids will
have
obvious
walls and
bias > 0



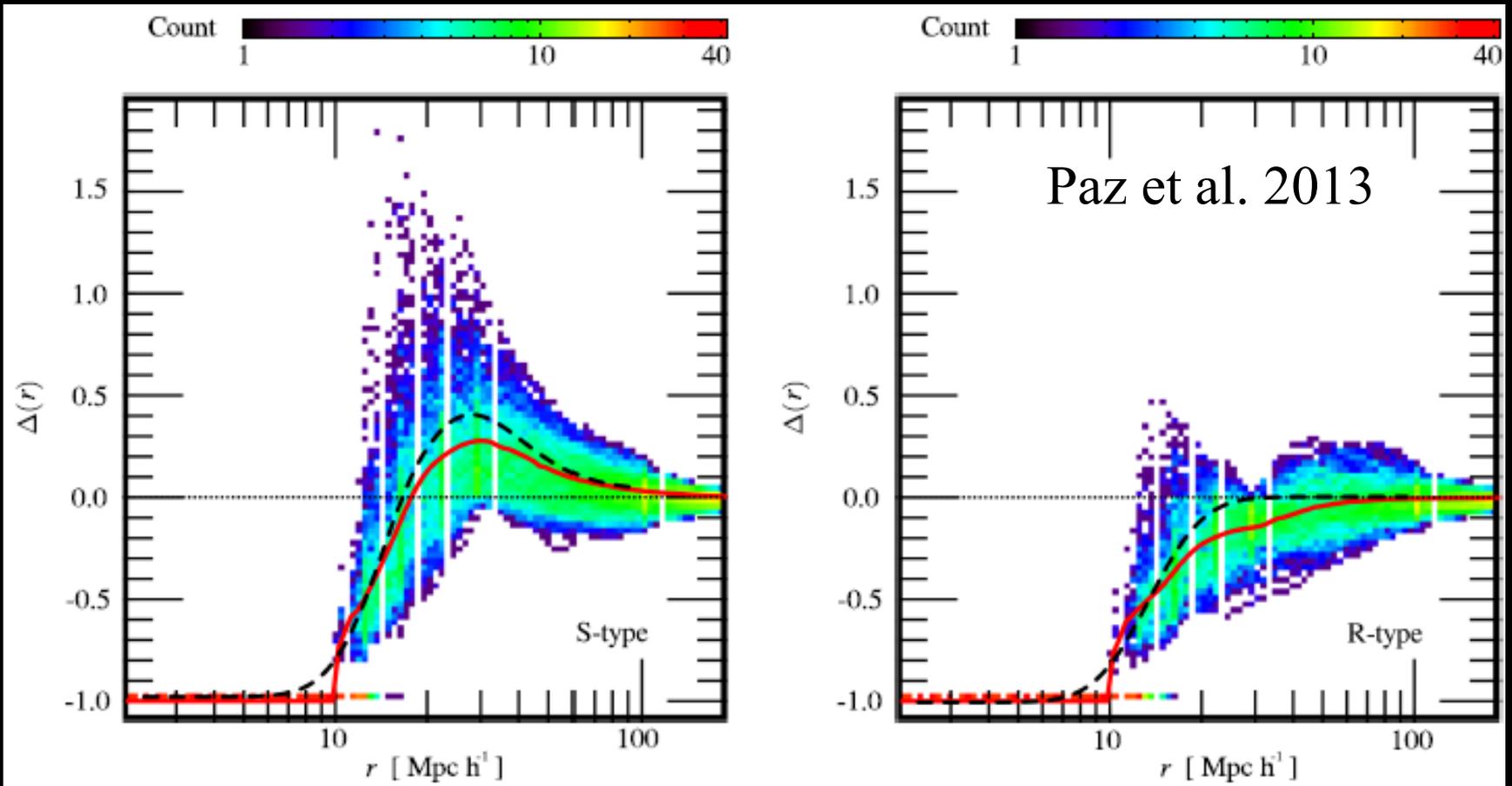
Big voids
will have
bias < 0
and less
obvious
walls



Seen in simulations ...



... and in data

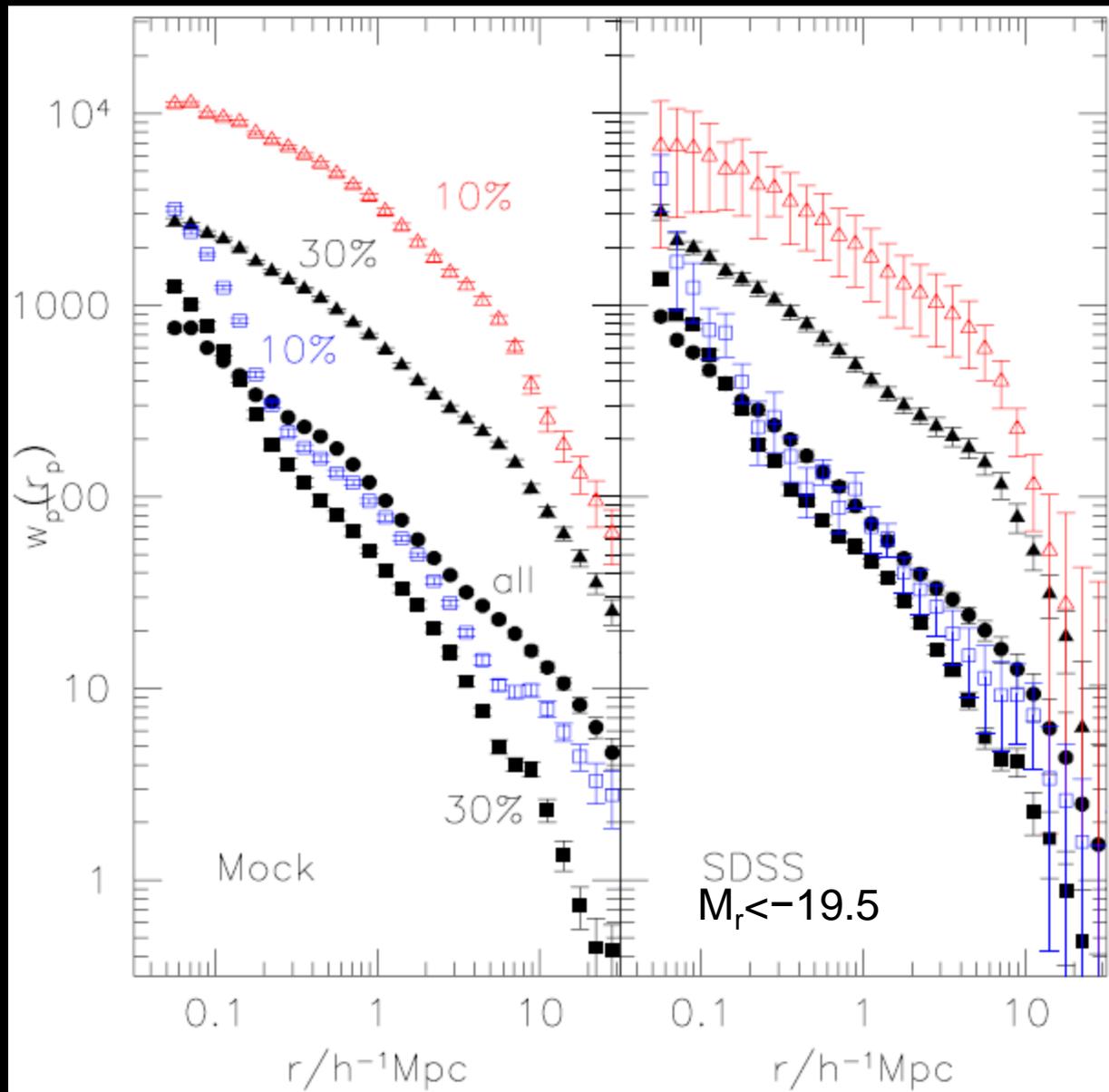


Work in progress to see if model also quantitatively OK

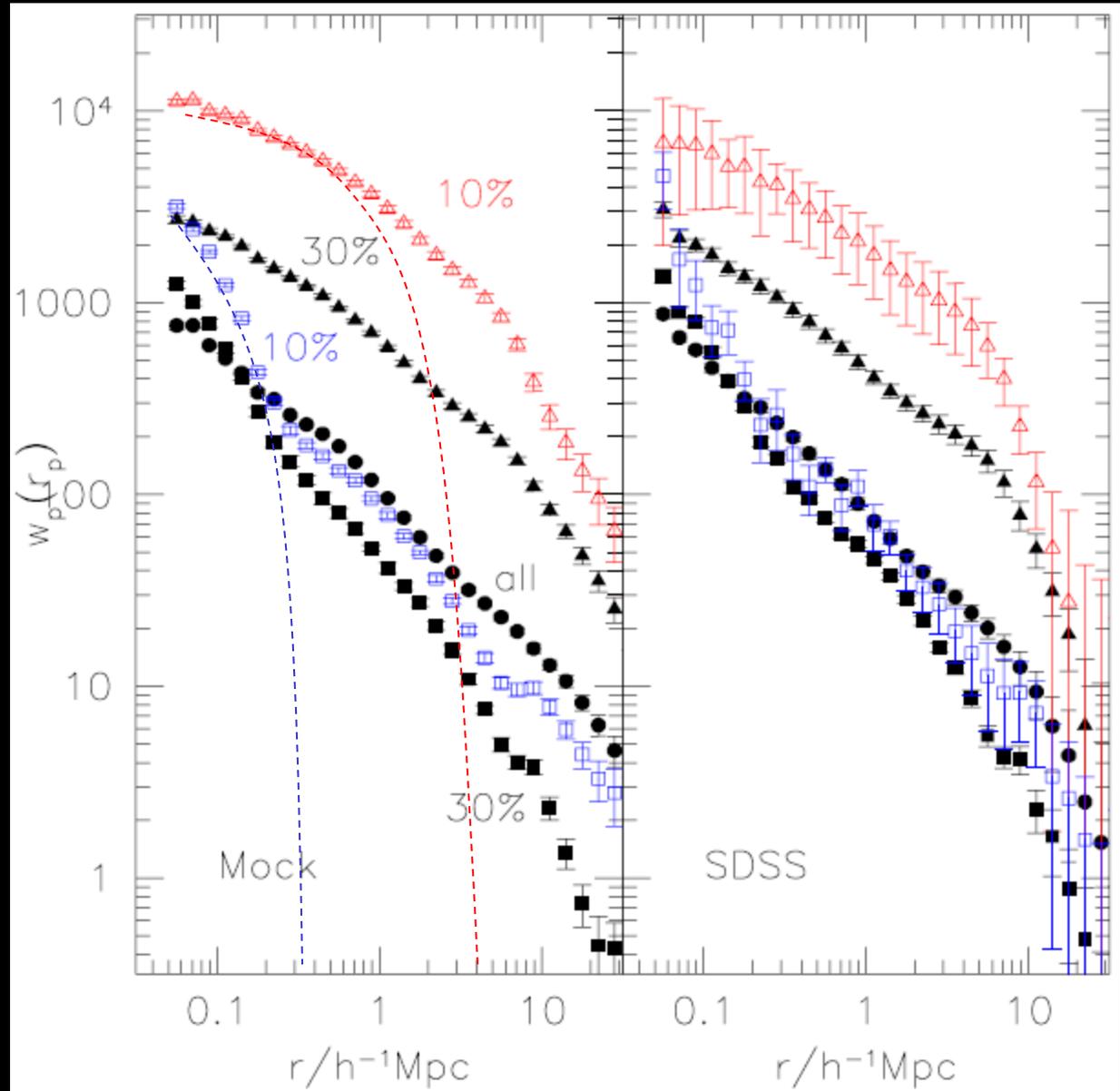
Since some voids have $b > 0$
and others $b < 0$,
some 'voids' have bias = 0.

Generically, bias=0 is possible for
sufficiently large sufficiently
underdense regions.

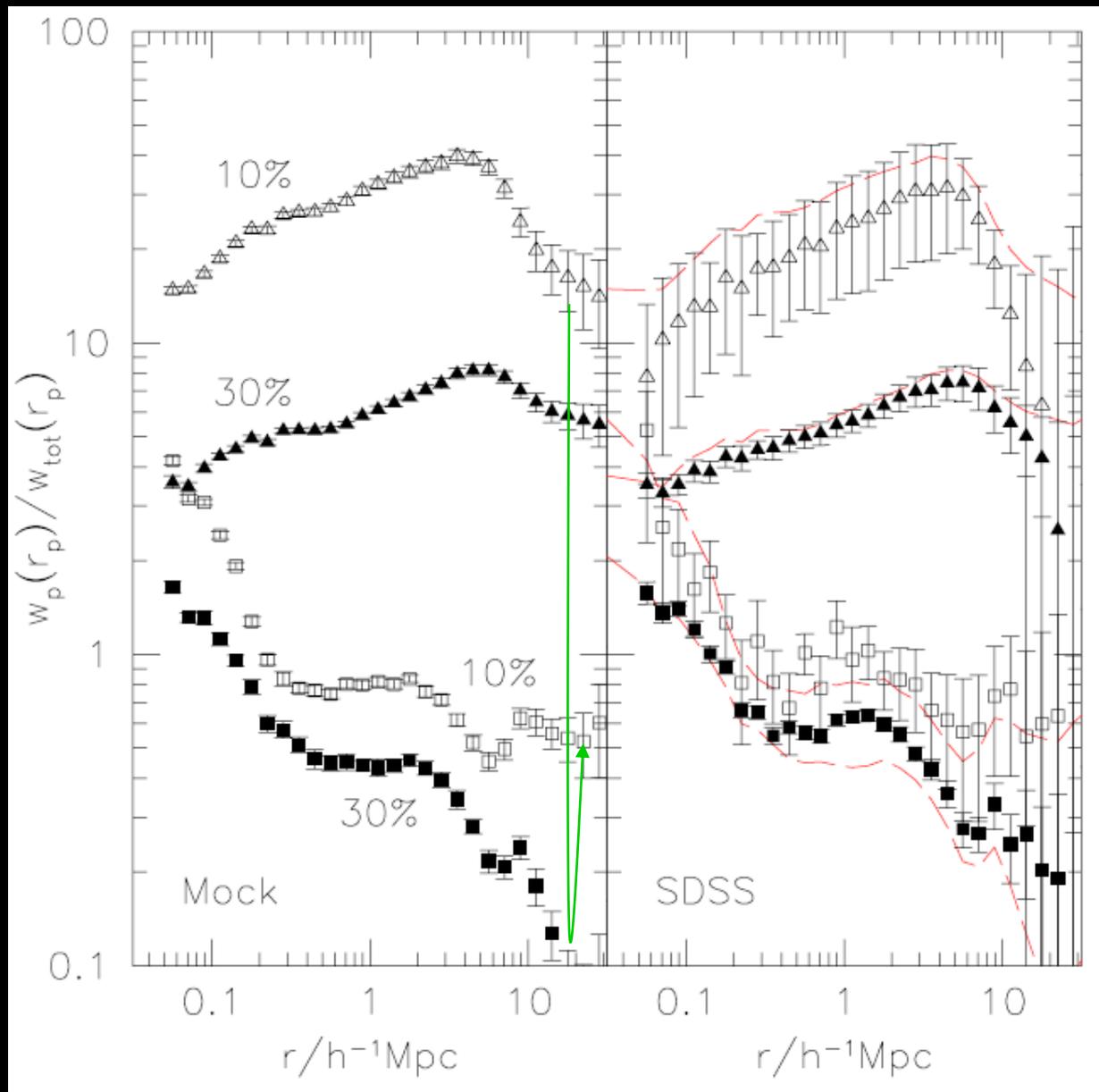
- Assume cosmology \rightarrow halo profiles, halo abundance, halo clustering
- Calibrate $g(m)$ by matching n_{gal} and $\xi_{\text{gal}}(r)$ of full sample
- Make mock catalog assuming same $g(m)$ for all environments
- Measure clustering in sub-samples defined similarly to SDSS



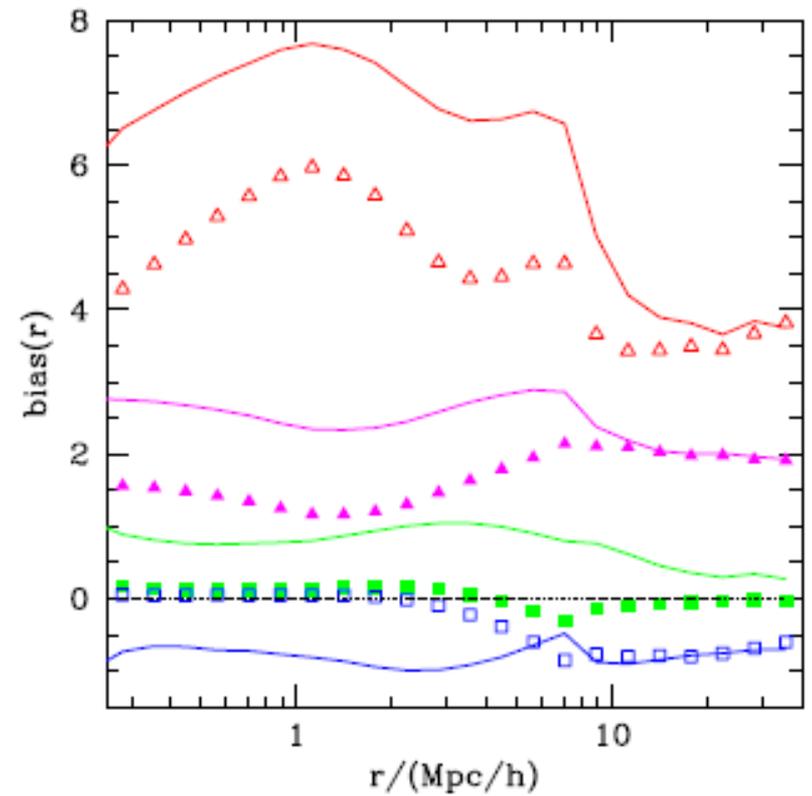
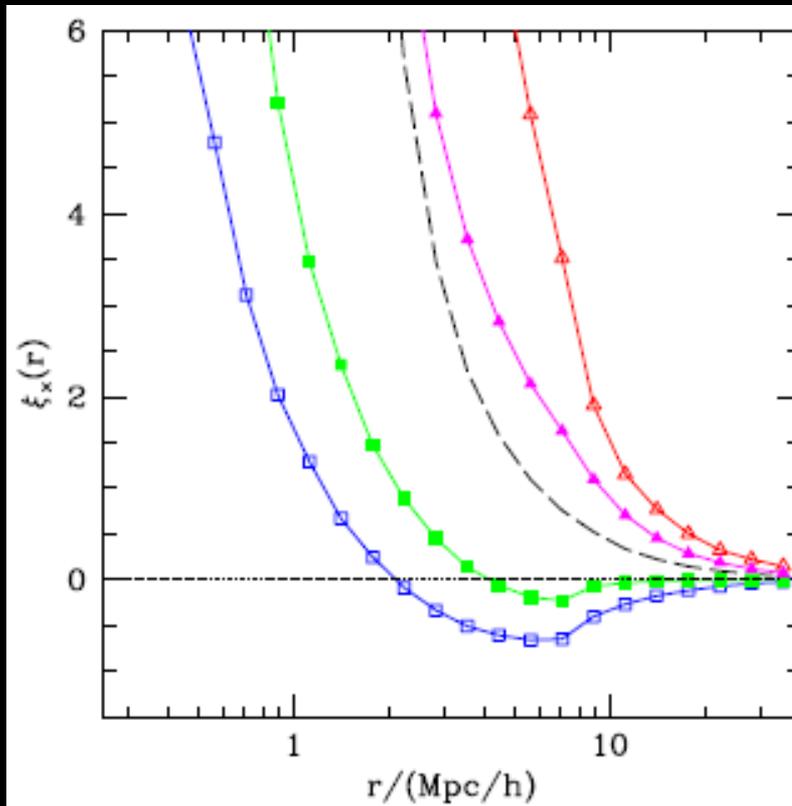
- Environment = neighbours within 8 Mpc
- Clustering stronger in dense regions
- Dependence on density NOT monotonic in less dense regions
- Same seen in mock catalogs; little room for extra effects



- Galaxy distribution remembers that, in Gaussian random fields, high peaks and low troughs cluster similarly (but with opposite signs)



Auto-correlation only sees b^2



Bias from cross correlation $\propto b$ is indeed monotonic, and crosses 0

Some interest in using $b=0$ objects as standard rods (Hamaus et al. 2013)

- These will depend on tracer population.
- SDSS Main Galaxy sample in Abbas-Sheth had $b \sim 1$, so underdense patches of size $8 \text{ Mpc}/h$ in this sample had $b=0$.
- In LRG sample, $b=0$ for voids of size $20 \text{ Mpc}/h$.

Nonlocal bias

- Bias is generically expected to be k-dependent
- Should we expect angular dependence as well?

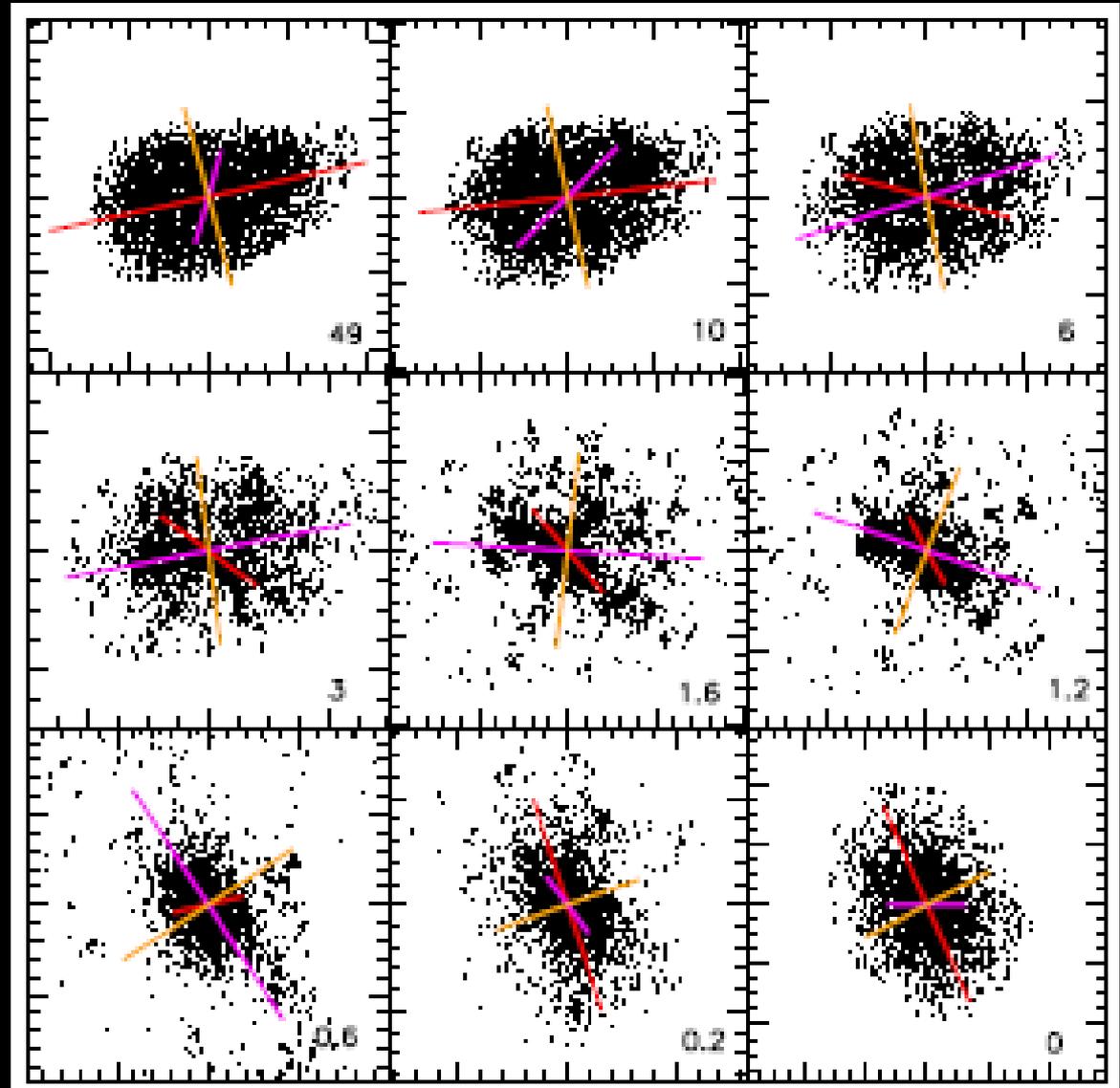
Triaxial collapse

Halos identified
using ellipsoidal
overdensity

Spherical
overdensity
masses OK to \sim
10%

Shapes differ by \sim
40%

Despali, Tormen,
Sheth 2013

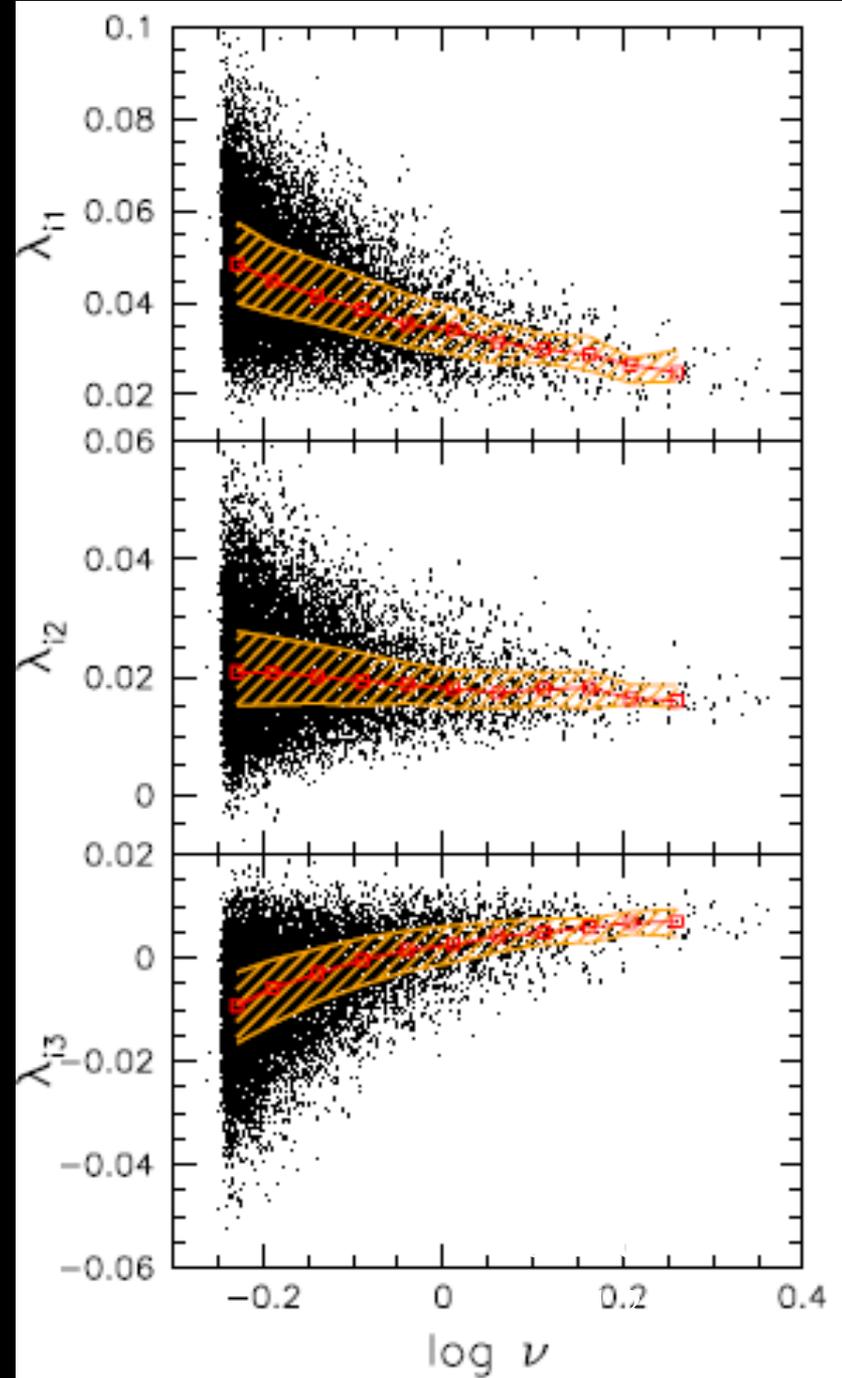


Halo formation depends on more than trace of Deformation tensor

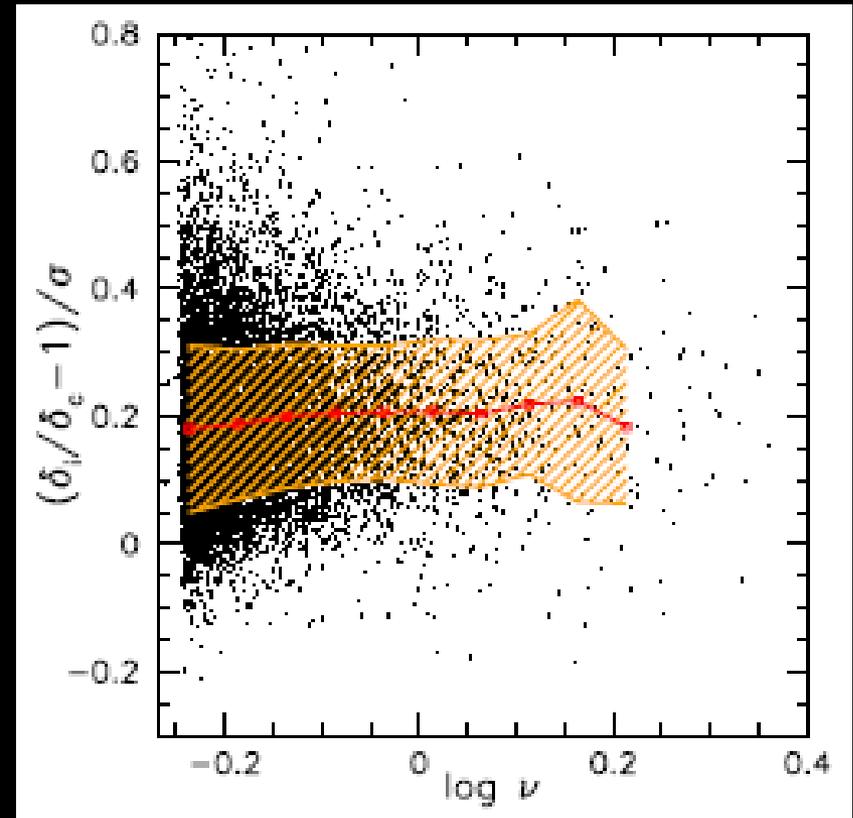
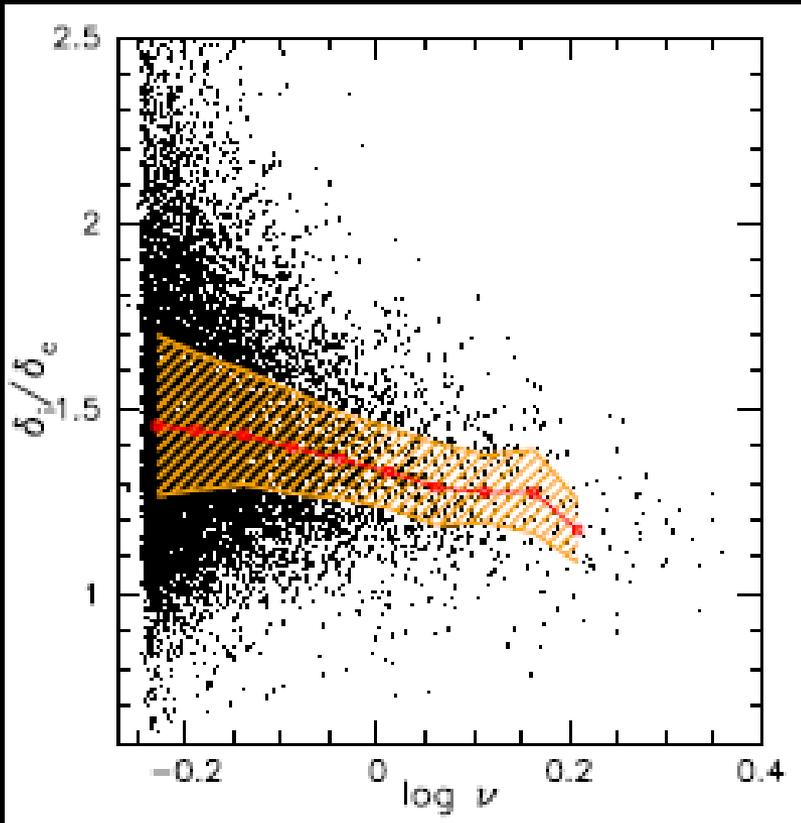
Bond & Myers 1996;
Sheth, Mo, Tormen 2001

- Not all eigenvalues have same sign

Despali, Tormen, Sheth 2013



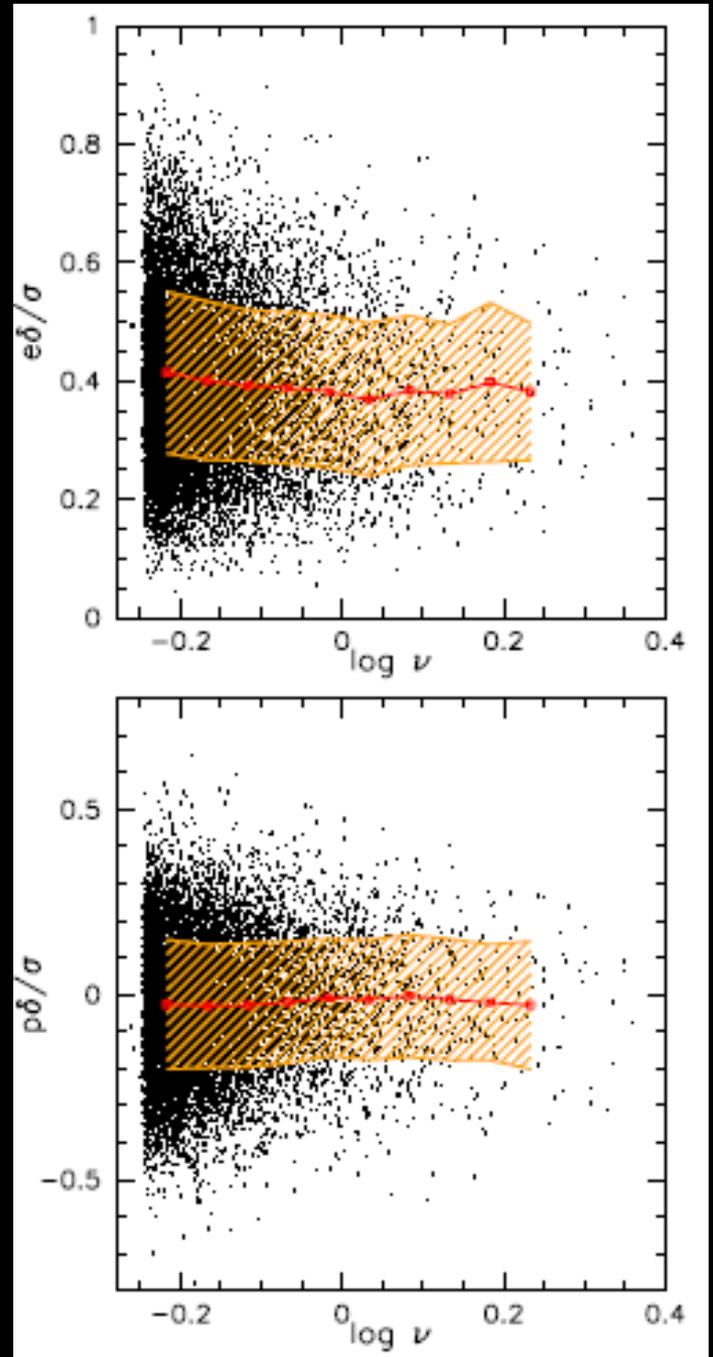
More massive protohaloes are rounder (virialized haloes are not)



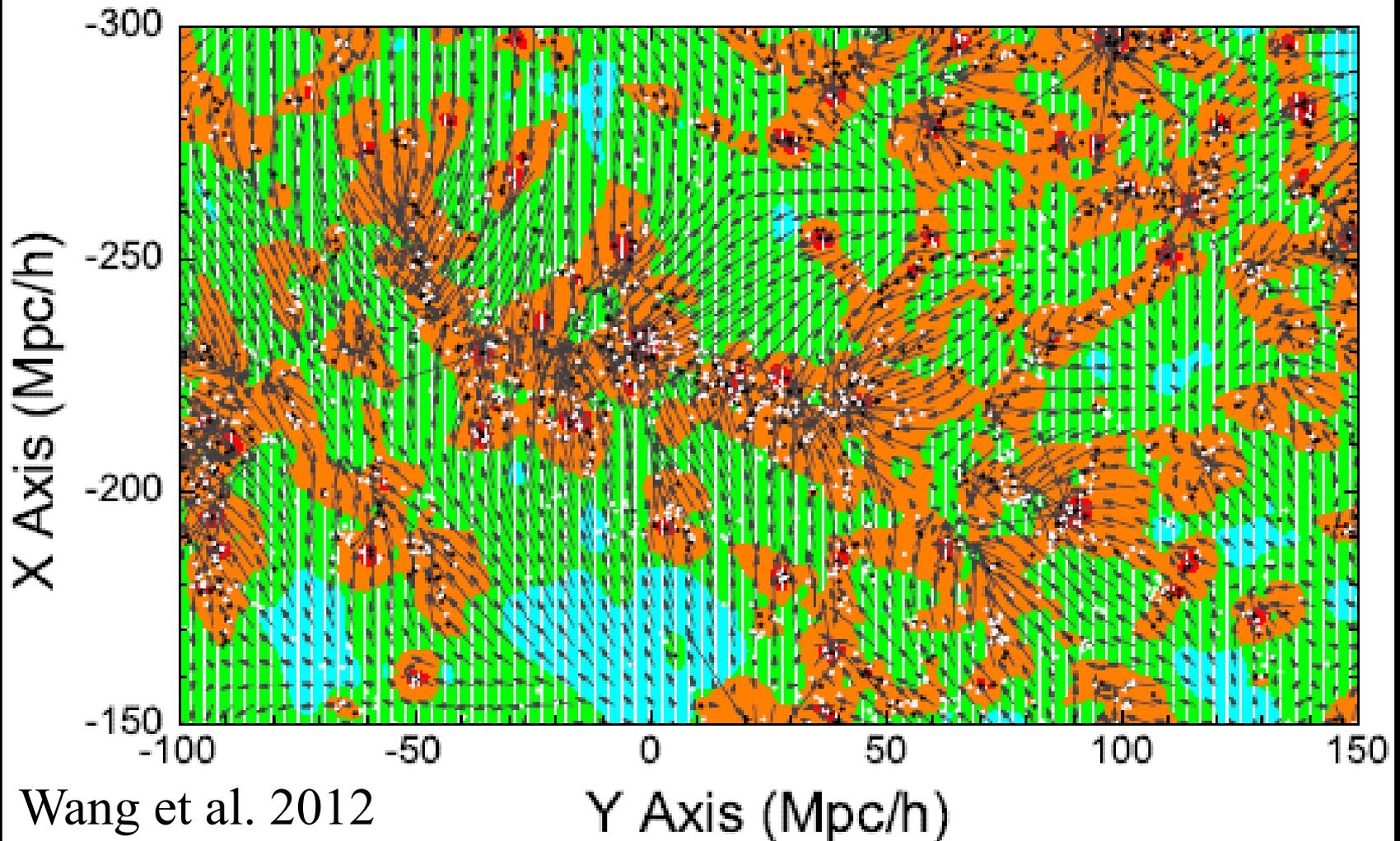
Despali, Tormen, Sheth 2013

Overdensity,
ellipticity,
prolateness all
scale with σ ,
so decrease at
large mass

Despali, Tormen, Sheth 2013



Can infer density, velocity, tidal fields



Can we model this?

Halo formation depends on more than trace of DefTensor

- In triaxial collapse models critical density for collapse depends on e, p (SMT2001)
- Will study simpler case in which new parameter is traceless shear q (this is the quadrupole in perturbation theory)
- Ask for largest scale on which

$$\delta > \delta_c (1 + q/q_0)$$

‘Stochastic’ barrier

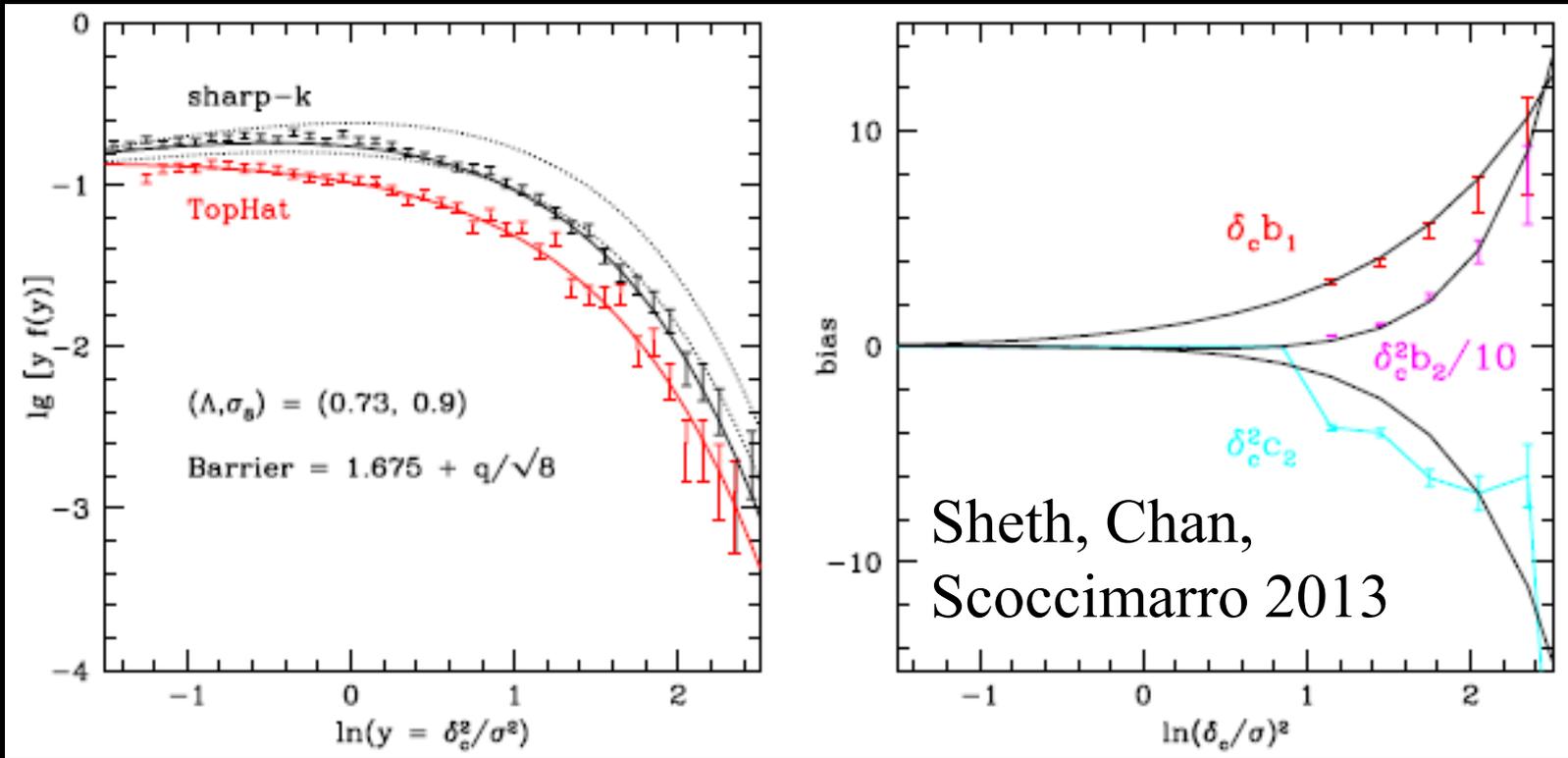
- Traceless shear q is non-Gaussian, $\chi^2(5)$, that is uncorrelated with δ
- Asking for largest scale on which

$$\delta > \delta_c (1 + q/q_0)$$

is like doing barrier crossing problem for 6d walks

- Can think of this as a stochastic barrier, whose height is different at each step (because of q)
(Sheth-Tormen 2002)

6d walks with correlated steps



$$v f(v) \approx \frac{v e^{-(v + \sqrt{\delta_c^2/q_c^2})^2/2}}{\sqrt{2\pi}} \left[1 - \frac{\text{erfc}(\Gamma v/\sqrt{2})}{2} + \frac{e^{-\Gamma^2 v^2/2}}{\sqrt{2\pi} \Gamma v} \right]$$

Can also do as 1d nonGaussian (δ - q) walks (Musso, Sheth 2014)

Large scale bias

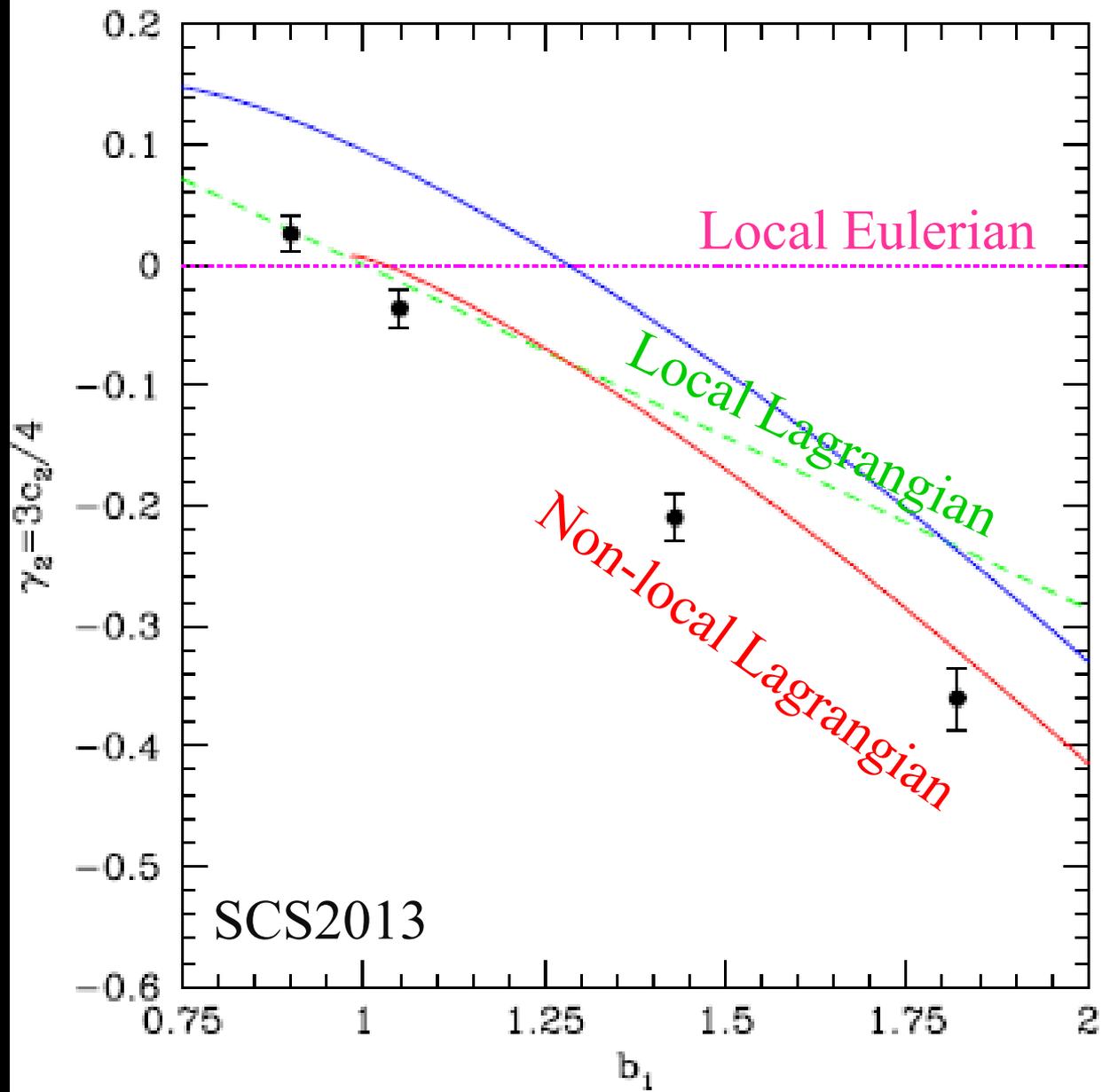
- The local bias model

$$\begin{aligned}1 + \delta_h &= f(s|\delta_L(\delta))/f(s) \\ &= 1 + b_1 \delta_L(\delta) + b_2 \delta_L(\delta)^2 + \dots\end{aligned}$$

- ‘Nonlocal’ bias means things other than δ matter
- Even if $f(s|\delta_L(\delta))/f(s)$ depends only on δ_L , then bias with respect to δ will seem nonlocal because mapping between δ_L and δ is ‘nonlocal’.
- If q matters, even Lagrangian bias is ‘nonlocal’.

Account for additional nonlocality from contribution of tidal term to nonlinear evolution $\delta(\delta_0, q_0)$ to get Eulerian bias.

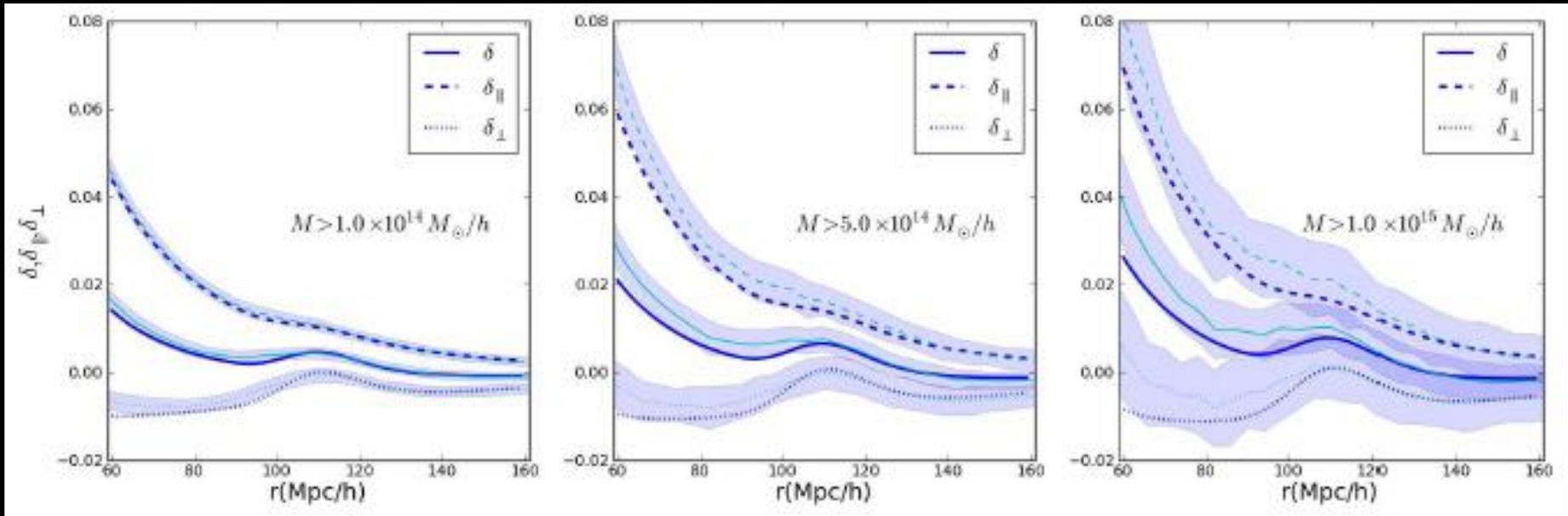
$$\begin{aligned}1 + \delta_h^E(\delta, q^2) &= (1 + \delta)(1 + \delta_h^L) \\&= (1 + \delta) \left(1 + b_1^L \delta_0 + b_2^L \frac{\delta_0^2}{2} + c_2^L \frac{q_0^2}{2} + \dots \right) \\&= 1 + b_1^L \delta_0 + b_2^L \frac{\delta_0^2}{2} + c_2^L \frac{q_0^2}{2} + \delta + b_1^L \delta_0 \delta \\&= 1 + \delta (b_1^L + 1) + \frac{\delta^2}{2} (8b_1^L/21 + b_2^L) \\&\quad + \frac{q_0^2}{2} (c_2^L - 8b_1^L/21).\end{aligned}$$



Summary

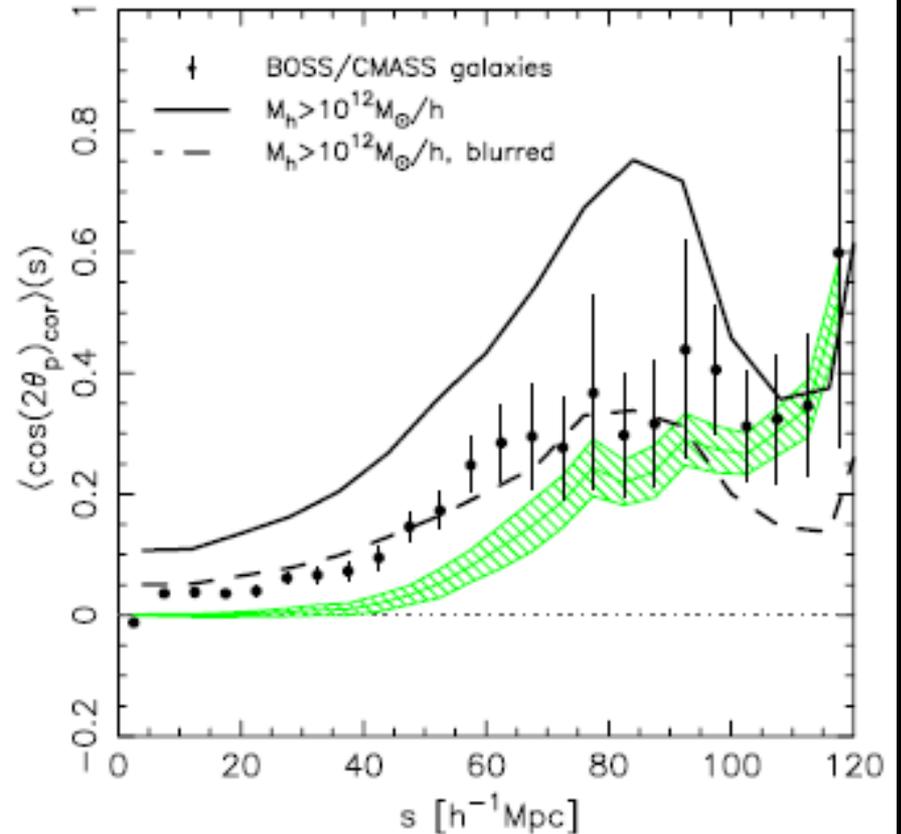
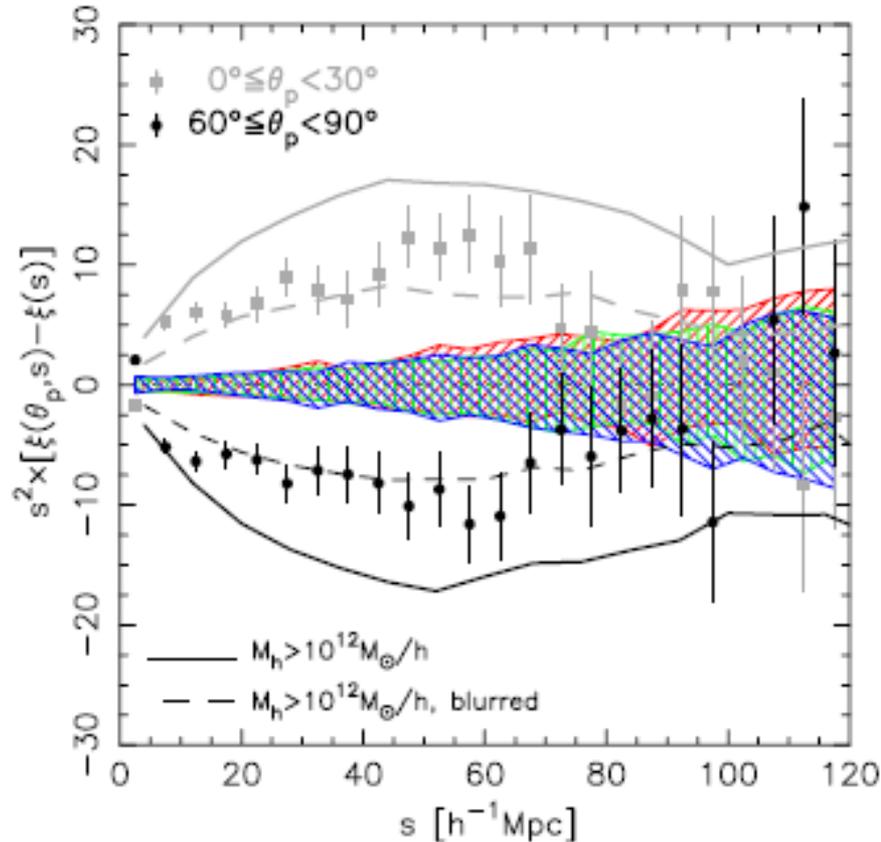
- Getting closer to a model which includes nonlocal, nonspherical effects, and reconciles peaks/halos (Castorina-Sheth 2013)
- These generate k -dependent bias (monopole), as well as anisotropic bias (e.g. quadrupole), even in real-space
- Nonlocal bias matters at high mass
- Useful for making physically motivated ‘fitting formulae’ which simplify data analysis

Halos aligned with LSS



- Measurements in sims from Faltenbacher et al. (2012)
- Model assumes alignment with large-scale shear field generates quadrupolar signal proportional to same q which makes nonlocal bias (Papai & Sheth 2013)

Also seen in CMASS



- Halos more strongly aligned than galaxies (modeling this is work in progress)

Summary

Its always good to step up; first passage problem with correlated steps 'solved' using only 3 variables.

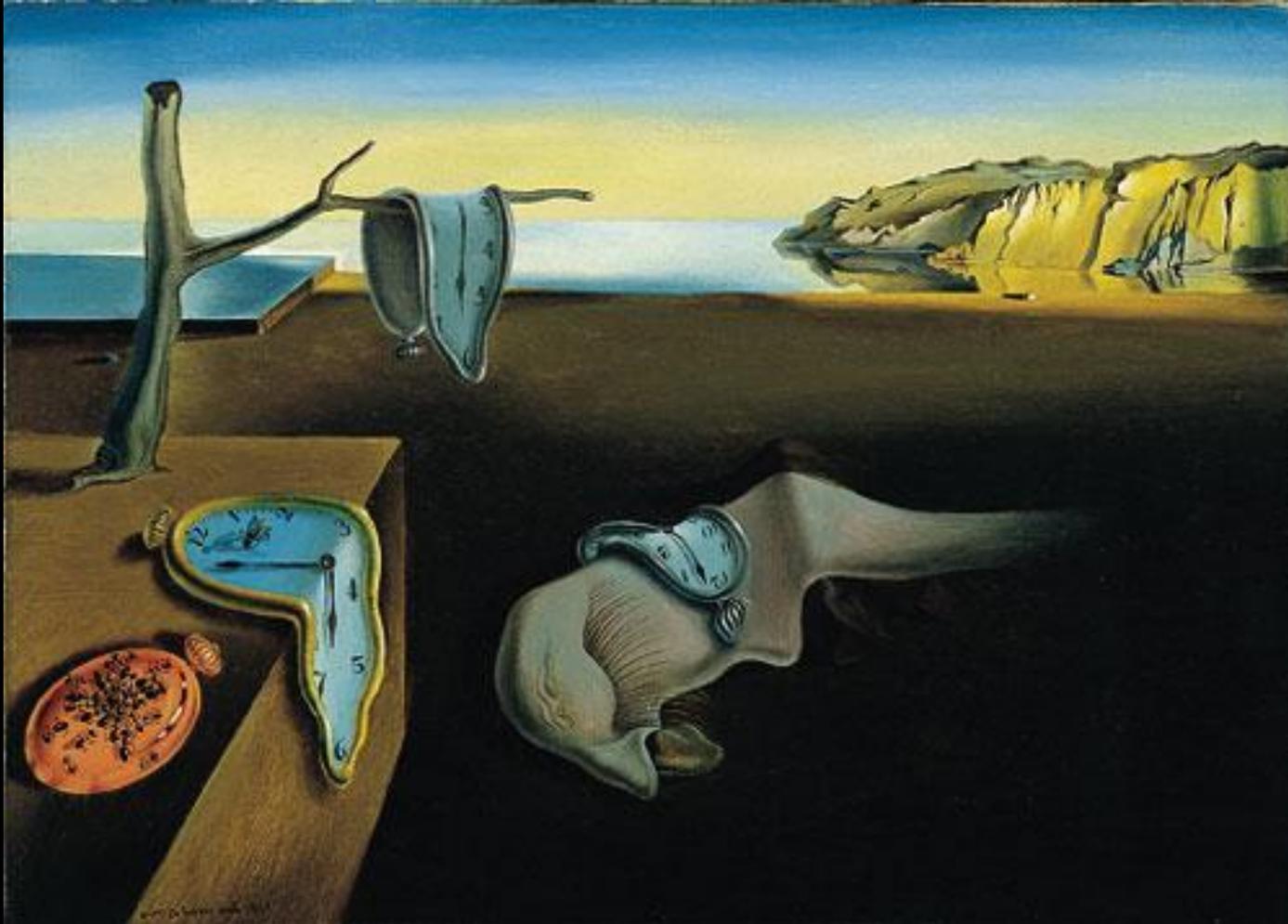
Markov velocities are the next most natural (Ising-model like) generalization of the usual Markov heights model; good approximation for CDM-like $P(k)$!

Self-consistent model must only average over special subset of walks. Peaks are a good choice, for which closed form expressions are now available.

Must incorporate stochasticity in halo formation from tidal field and (mis-alignment with!) proto-halo shapes.

Tidal field leaves signature on halo abundances, clustering, especially in higher-order statistics of highly clustered objects (typically high-mass halos).

Hierarchical clustering in GR



= the persistence of memory